

Design and Certification of an Aircraft Major Modification: Ka-Band Satcom System for Airbus A320 Family

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Thesis to obtain the Master of Science Degree in

Aerospace Engineering

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November 2019

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To my aunt Fátima, who always desired so much this my achievement as much as I did.

Acknowledgments

I would like to start off by expressing my gratitude to Professor Afzal Suleman. All the availability provided in the correct moments to give the required guidance was indispensable. Furthermore, thank you for allowing me work on a subject of my interest.

Secondly, I would like to thank Diogo Alvim, my supervisor in Jet Aviation, for all the support provided in this dissertation during my traineeship. It was invaluable all the guidance and availability shared with me. In addition, I would also like to declare how thankful I am for the support shown outside of the dissertation. Thank you for all the concern shown about my well being during all this stage.

Thirdly, I would like to express my gratitude to Jet Aviation for receiving me in this journey and providing all the resources required to perform this dissertation. Furthermore, thank you for all the training, knowledge shared with me and the confidence shown in my daily work in the beginning of my professional career. In addition, thank you to all the amazing colleagues that I met there and who played an important role in my success on this thesis.

In fourth place, I would like to thank my friend Maria José Garcia for all the support given in my arrival in Switzerland and all the good moments afforded while I was working in this dissertation. This made me feel as if I was at home.

In fifth place, I would like to thank all my friends who shared this journey with me and who were an important factor for this achievement. A special thanks to Joana Melo, an amazing person who I was lucky to meet in the last years of university, for all the time spent together and the constant concerning shown with my well being.

Finally, I would like to thank all my family for always pushing me up and believing in my capabilities. Thank you to my grandparents Helena, Rosa and Fernando for the unconditional love and support. Thank you to my sister Joana for the shared brotherhood independently of the distance which separate us. Thank you to my uncle Pedro for the constant presence in my life and all the key advices to face the life challenges and be successful. Thank you to my aunt Fátima for being my second mother, always raising me and giving me the discipline to be a good person. Lastly, thank you to my mother Olinda for the patience and for always putting me first whenever I needed it. Thank you for the unconditional love independent of the life circumstances. Thank you to these last to very important persons on my life for giving me everything I needed.

Resumo

Com o aumento do número de aviões no céu nas últimas décadas, um novo produto de mercado emergiu, as modificações de aeronaves. Com o apoio da Jet Aviation, uma empresa especialista no ramo, este trabalho percorre todas as etapas necessárias para se pedir um Supplement Type Certificate (STC) para realizar a instalação de um sistema ka-band satcom, classificado como modificação grande, na estrutura primária da aeronave, respeitando os regulamentos da EASA e da FAA. As principais etapas abordadas são o desenvolvimento do design, os requisitos de certificação, as análises, a instalação, os testes experimentais e a documentação necessária. As provisões estruturais deste sistema são desenvolvidas internamente e baseiam-se no standard industrial ARINC. Os ganhos do uso deste standard no design são abordados. O corpo desta tese é o desenvolvimento de uma optimização paramétrica das provisões estruturais em termos de redução de peso e tempo de vida de fadiga. Para a realização do mesmo, três modificações estruturais em três componentes diferentes do design inicial são definidas e são criados sete novos designs através de combinações dessas três modificações. As sete hipóteses são sujeitas a uma análise estática realizada por meio de uma combinação entre simulação de elementos finitos e métodos analíticos, para verificar a sua integridade estrutural. Adicionalmente, uma análise de fadiga é conduzida sobre os componentes críticos para estimar o novo tempo de vida de fadiga dos designs. Como resultado, é determinado o design ótimo de entre os sete em estudo.

Palavras-chave: Modificações de aeronaves, Sistema *ka-band satcom*, Certificação, Projecto mecânico, Análise estática, Análise fadiga

Abstract

With the increase of the number of aircraft in the sky in the last decades, a new business product emerged, the aircraft modifications. With the support of Jet Aviation, a company specialized in the field, this work goes through all the necessary steps to apply for a Supplemental Type Certificate (STC) to perform an installation of a ka-band satcom system, classified as a major modification, in the primary structure of an aircraft, by complying with the EASA and FAA regulations. The main steps covered are the design development, certification requirements, analyses, installation, experimental tests and required documentation. The structural provisions for this system are developed in-house and are based on an ARINC industry standard. The gains of using this standard in the design are discussed. The main object of this thesis is the development of a parametric optimization study to the structural provisions in terms of weight reduction and fatigue life. To conduct that, three structural modifications in three different components of the initial design are defined and are created seven new designs composed by combinations of those three modifications. The seven hypotheses are subjected to a static analysis performed by a combination of Finite Element Method (FEM) simulation and analytical methods to verify their structural integrity. Furthermore, a fatigue analysis is conducted to the critical components to estimate the new fatigue life of the designs. As result, is determined the optimal design between the seven in study.

Keywords: Aircraft modifications, Ka-band satcom system, Certification, Mechanical design, Static analysis, Fatigue analysis

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Nomenclature

Abbreviations

- AEEC Airlines Electronic Engineering Committee
- AMC Avionics Maintenance Conference
- AMM Aircraft Maintenance Manual
- APM Airplane Personality Module
- ARINC Aeronautical Radio Incorporated
- **CFR** Code Federal Regulations
- CG Centre of Gravity
- **DOA** Design Organization Approval
- **EASA** European Aviation Safety Agency
- FAA Federal Aviation Administration
- FMA Fuselage Mounted Antenna
- FSEMC Flight Simulator Engineering and Maintenance Committee
- GAG Ground-Air-Ground
- GA General Aviation
- ICAO International Civil Aviation Organization
- ICA Instruction for Continued Airworthiness
- IPC Illustrated Part Catalogue
- KANDU Ku/Ka-band Aircraft Networking Data Unit
- KRFU Ku/Ka-band Radio Frequency Unit
- **MODMAN** Modem and Manager
- **OEM** Original Equipment Manufacturer

SAE-ITC Society of Automotive Engineers-Industry Technologies Consortia

- SF Severity Factor
- SRM Structural Repair Manual
- **STC** Supplemental Type Certificate

Greek symbols

- α Fastener hole condition factor.
- β Hole filling factor.
- θ Bearing distribution factor.

Roman symbols

- A Area.
- C Yield factor.
- D Diameter.
- *E* Young's Modulus.
- *F* Ultimate or yield stress.
- *f* Applied stress.
- *g* Gravity Acceleration.
- *I* Moment of inertia.
- *K* Fatigue quality index.
- K_t Stress concentration factor.
- k_t Tensile efficiency factor.
- k_{br} Shear bearing efficiency factor.
- K_{tb} Bearing stress concentration factor.
- K_{tg} Stress concentration factor parametrize.
- K_{th} Local stress concentration factor.
- k_{tru} Tensile efficiency factor for transversal loads under ultimate condition.
- k_{try} Tensile efficiency factor for transversal loads under yield condition.
- L Length.
- M Moment.

- MS Safety Margin.
- N_f Fatigue life number of cycles.
- P Force.
- *R* Reaction forces.
- *S* Shear loads.
- T Tensile loads.
- t Thickness.

Glossary

- **CFD** Computational Fluid Dynamics is a branch of fluid mechanics that uses numerical methods and algorithms to solve problems that involve fluid flows.
- **CSM** Computational Structural Mechanics is a branch of structure mechanics that uses numerical methods and algorithms to perform the analysis of structures and its components.

Chapter 1

Introduction

1.1 Present State of Aeronautic Industry

Since the beginning of air transportation's history, this type of transport had a huge and important impact in people's lives and also in the world economy. Now-a-days, this tendency continues to be observable, the number of transported passengers increases every year [1]. This continuous demand for a quick transport for long distances in a relatively short time, made the aeronautic industry develop in a large scale. This huge development was only possible with the great advances of major technological innovations, such as the introduction of jet aircraft for commercial use in the 1950s [2]. In the modern days, the major on going innovation is the introduction of composite materials in more than 50% of aircraft's structure. Aircraft Original Equipment Manufacturers (OEMs) as Boeing and Airbus already achieved this high percentage with the Boeing 787 and Airbus A350 XWB [3]. In parallel, the fast technological evolution and trends changes created new opportunities of business products in the industry, more specifically in the sector of aircraft alterations/changes. The nomenclature alteration or change rely on the regulation authority which the modification must be subjected. Alteration is used for Federal Aviation Administration (FAA) and change for European Aviation Safety Agency (EASA). These two regulations authorities are presented in more detail in section 1.3.

1.2 Aircraft Modifications

The definition of aircraft modification comes in two forms: Alterations/Changes and Repairs. The first form refers to the modifications where it is added new equipments or features to the aircraft. The second form refers to modifications where it is re-established the original strength and integrity of the damaged areas in the aircraft. In addition, these two forms can be classified in major and minor modifications. The definition of these two classifications has suffered several changes since the beginning of industry. These definitions' update were introduced in order to give a better clarity and guidance to the companies which provide these types of services. Now-a-days, the updated definition for these concepts is given by two documents, Federal Aviation Regulation (FAR) PART 1 and 43. These two documents, produced

by FAA, illustrate and distinguish major from minor alterations and repairs. As the main focus of this thesis falls upon changes/alterations, the official definition for major and minor changes/alterations are presented.

FAR PART 1 states that a major alteration is "an alteration not listed in the aircraft, aircraft engine, or propeller specifications-

- 1. That might appreciably affect weight, balance, structural strength, performance, powerplant operation, flight characteristics, or other qualities affecting airworthiness; or
- 2. That is not done according to accepted practices or cannot be done by elementary operations."

On the other hand, a minor alteration is simply defined as "an alteration other than a major alteration." [4]

Any of these modifications need to be certified by a competent authority, unless the company which is performing the modification is certified by an airworthiness authority showing that it is capable to autocertify their own modifications. However, one of the options to certify a modification passes through the creation of a supplemental type certificate (STC). This option to certify a modification is very expensive, consequently it is only used when there is an interest in performing the same modification in several aircraft. A STC is a document where the new features added to the initial aircraft are described. To apply for an STC several different documents must be prepared. These will prove that there is compliance with several certain requirements. These documents start with the CAF - Classification Assessment Form, where the modification is introduced and also defined as a major or minor alteration, or repair. And it goes until the instructions for continued airworthiness, known as Instructions for Continued Airworthiness (ICAs). An important document which proves that after the accomplished modification, the aircraft continues to meet its appropriate airworthiness, noise, and emissions standards and states the alterations in maintenance program and inspection intervals [5, 6].

1.3 The Civil Aviation Authorities

Since the aviation early times and subsequent rapid growth, every country found necessary the creation of autonomous institutions and national authorities to guarantee flight safety. This was the birth of civil aviation authorities. These also known as airworthiness authorities which have the following main tasks [5]:

- To prescribe airworthiness requirements and procedures;
- To inform the interested parties regarding the above-mentioned prescriptions;
- To control aeronautical material, design, manufacturing organizations, and aircraft operators;
- To certify aeronautical material and organizations;

On April 4th 1947, the International Civil Aviation Organization (ICAO) was established with main goals of developing the principles and techniques of international air navigation and achieve a standardized operation for a safe and efficient air service. This standardization was achieved with the elaboration of 18 annexes named as International Standards and Recommended Practises [5].

Presently, there are two main independent entities which groups several civil aviation authorities of different countries. In the European space, there is the European Aviation Safety Agency (EASA) which succeeded the Joint Aviation Authorities (JAA) and represents all Union European state members [5]. In the United States, there is the Federal Aviation Authority (FAA) which represents all their states. These two authorities play an important role in several areas such as rulemaking or inspections, training, and standardization programs [5]. For the scope of this thesis, the most relevant function of these two authorities is the certification and approval of STCs.

1.4 Jet Aviation AG

Jet Aviation AG is a recognized leader company in the business aviation industry. It was established in 1967 by providing maintenance services in Basel, Switzerland, where presently is its headquarters. Now-a-days Jet Aviation offers a variety of aircraft-support services, ranging from maintenance, completions and refurbishments to aircraft management and charter services [7]. As a recognized jet aircraft repair station, Jet Aviation holds several authorizations and approvals from EASA, FAA and other seventeen different national aviation authorities.

The companies' engineering hub is based in Basel and provides custom solutions while meeting customer's specifications and ensuring technical feasibility and certification requirements. The engineering teams are divided in two sections, the completions side and maintenance. These teams work close to sales, interior design, production and installation teams since the initial conceptual design to the delivery. Completions side has the main focus of providing the integration, customization and upgrade of equipments and in-flight entertainment in several Airbus and Boeing aircraft types. While the maintenance side, provides engineering and certification services to custom modifications for any aircraft of large category [7]. Regarding, the engineering part, the maintenance side provides cabin layouts changes, installation and upgrade of navigation and communication systems, repairs and most important for the scope of this work, the development, installation and upgrade of satcom systems. These modifications are only possible because Jet Aviation has several Design Organization Approvals (DOAs) from EASA, FAA and other civil aviation authorities [7].

Inside the satcom systems there is the ka-band satcom system which is the main target for this thesis.

1.5 Ka-Band Satcom System

1.5.1 Generic Concept

Now-a-days, the state of the art in aircraft communication via satellite is ka-band satcom antenna which provides to the aircraft, data transmission and reception in high frequencies between 26.5–40 gigahertz (GHz). The ka-band stands for "K-above" because it is the upper part of the original NATO K band as shown in figure 1.1. The ka-band antenna predecessor was the ku-band antenna. The bandwidth of the ku is around 2GHz for uplink and 1.3GHz for downlink with actual contiguous bandwidth allocation of less than 0.5GHz per satellite. In comparison, the ka-band satcom has a bandwidth of 3.5GHz for both uplink and downlink [8]. Having a wider bandwidth, consequently greater resiliency to interference is achieved. Presently, as it is required more and more wide bandwidth signals, the ka-band antenna offers additional frequencies to communicate [9]. In parallel also, there is an increase of data transfer due to the higher frequencies. Other reason why the ka-band is attractive as a satcom solution is that requires smaller terminals which allows the ka-band satcom be made available for new markets such as mobile platforms [8].



Figure 1.1: Satellite Bands [9].

This system in combination with the on-board technologies, allows the aircraft's passengers to have access to a broadband connectivity in a wide area of the globe and so they can connect to the social media and communicate online with high speed internet velocity, as if they were at home [9]. Another advantage is that it can provides faster updated information to the pilots regarding weather conditions or other required information, however this system is not the critical one to obtain that information neither to replace the one which is critical. Figure 1.2 presents the environment which provides the communication between the aircraft and ground stations, and the coverage map of the ka band satcom provided by Honeywell JetWave.

1.5.2 Composition

The ka-band satcom system can be divided in two distinct parts. The first refers to systems required for the correct functionality of the antenna. All the fundamental systems are described in chapter 2. In Jet Aviation all of these systems are bought from a supplier.



(a) Scheme of ka-band satcom antenna environment function- (b) Coverage map of the system installed by Jet Aviation [10] ality

Figure 1.2: characteristics of the ka-band satcom system.

The second part is the structural part which is the mechanical interface between the antenna and aircraft, where its ultimate goal is to withstand all the structural loads during a flight. These part is composed by several components which are described in detail in chapter 3. Most of this structure is fully developed in-house by Jet Aviation and this is the part that will be studied in order to be optimized in terms of weight and durability, without forgetting the certificability.

1.5.3 Certification - Supplemental Type Certificate

With the installation of ka-band satcom system, the aircraft's structural strength will be affected due to the local introduction of additional flight loads, because new structural components are being added to the primary structure. In addition, there will be changes in the aircraft's airworthiness limitations. New intervals and means of inspection must be defined. Finally, this modification will increment the aircraft's drag, but with a reduced impact in aircraft performance. Taking into account the points mentioned before, this modification is classified as a major change [11]. Since Jet Aviation doesn't have rights to auto-certify major changes, and intend to perform this modification several times in many aircraft of the same type, the profitable way to certify it is to apply for a STC in an airworthiness authority.

1.6 Project Presentation

During my traineeship, my main role was to contribute for the ka band antenna projects, where our team developed the structural provisions and systems installation for a few different aircraft types. I had a pleasure to help on these developments in airplanes as Boeing 747 variant -300 and -400 and some variants of Boeing 737 Family.

With the interest of a customer to install the ka-band satcom system in his aircraft, an Airbus A319, a new project rose up, the development of ka-band satcom system STC for Airbus A320 aircraft family. Therefore, the first aircraft types included in this STC are the A319 and A320 CEO (Current Engine Option) and NEO (New Engine Option).

1.7 Objectives

The main objectives to be achieved within the scope of this thesis are:

- Illustrate all the steps to certify a major modification in the primary structure of an aircraft. Going through the highlight of all the certification requirements that the modification must show compliance until the required documentation for STC approval;
- Show how a standard can be helpful for the industry development;
- Find several hypothesis for the optimal structural solution for the design, by modifying three structural components of the initial design;
- Using Computational Structural Mechanics (CSM) to perform static structural and fatigue analysis to study the several candidate hypothesis;
- Selection of the candidate hypothesis as optimal solution taking into account several different requirements;
- Show how the flight tests helps in the certification.
- Highlight the main conclusions and possible future works;

1.8 Thesis Outline

A brief description of the contents of the following chapters are now presented:

Chapter 2

An introduction to the Aeronautical Radio Incorporated (ARINC) Standards, the involved organizations in the process and their goals are presented. Detail description of the target standard, ARINC Characteristic 791, where is presented its definition, the required equipments and mechanical-interface requirements. Finally, the advantages of using this standard as a background in the design is also presented.

Chapter 3

A detailed description of the ka-band satcom structural base design for an Airbus A320 family, a Jet Aviation Solution, is presented. Starting with identification of the certification requirements, followed by the 3D modulation of the aircraft's airframe and complementary environment, and the selection of the optimum antenna installation location. Finally, geometry definition of new structural components which compose the developed structural provisions are presented.

Chapter 4

A parametric optimization is developed, where seven possible hypothesis of design are defined and presented. Furthermore, the methodologies used for the static and fatigue analysis are described.

Chapter 5

Results of the different analyses for the several hypothesis are presented. Followed by the selection of the optimal hypothesis taking in consideration several different requirements. In addition, the experimental results of the flight test for the vibration and buffeting tests are presented.

Chapter 6

Installation process aside of Reverse Engineering is illustrated. Additionally, the required documentation, which reflects the aircraft after modification state for requiring the STC, is presented.

Chapter 7

Conclusions are drawn and future work is proposed.

Chapter 2

ARINC 791 Standard

2.1 ARINC Standards

ARINC Industry Activities is one of the industry programs of Society of Automotive Engineers-Industry Technologies Consortia (SAE-ITC) which creates aviation industry committees and participates in related industry activities by providing technical leadership and guidance in order to benefit aviation [12]. Safety, efficiency, regularity and cost-effectiveness in aircraft operations are the aviation industry goals promoted by these activities.

In addition, ARINC Industries activities provides secretary services for the international aviation organizations such as Airlines Electronic Engineering Committee (AEEC), Avionics Maintenance Conference (AMC) and Flight Simulator Engineering and Maintenance Committee (FSEMC). While these entities develop technical standards for airborne electronic equipment, aircraft maintenance equipment and practices, and flight simulator equipment used in commercial, military and business aviation [12]. These standards are known as ARINC Standards and are published by SAE-ITC.

The ARINC Standards are divided in three classes and are defined as [12]:

- ARINC Characteristics "Define the form, fit, function, and interfaces of avionics and other airline electronic equipment. ARINC Characteristics indicate to prospective manufacturers of airline electronic equipment the considered and coordinated opinion of the airline technical community concerning the requisites of new equipment including standardized physical and electrical characteristics to foster interchangeability and competition."
- 2. ARINC Specifications "Are principally used to define either the physical packaging or mounting of avionics equipment, data communication standards, or a high-level computer language."
- 3. ARINC Reports "Provide guidelines or general information found by the airlines to be good practices, often related to avionics maintenance and support."

The focus of this work goes for the ARINC Characteristics which is the class that provides all the guide lines used in the studied design.

2.2 ARINC Characteristic 791

ARINC Characteristic 791 also entitled as "MARK I AVIATION KU-BAND AND KA-BAND SATELLITE COMMUNICATION SYSTEM" is divided in two parts, where each part is defined in an individual document.

The first part named as "PHYSICAL INSTALLATION AND AIRCRAFT INTERFACES" presents an overview of ku-band satcom and ka-band satcom systems. This defines the system provisions, attachments, cooling and inter-system wiring. Part 1 is the relevant part for this work because it gives the staring point for the design by defining the interface between the antenna and aircraft.

On the other hand, the part 2 entitled as "ELECTRICAL INTERFACES AND FUNCTIONAL EQUIP-MENT DESCRIPTION", as the name refer, it presents the interface definition of the satcom systems. To allow a simple aircraft integration, all signals crossing into or out of the communication system are documented in this part.

2.2.1 KU/KA-Satcom System Description

For a complete understanding of this characteristic, its definition and a block diagram of the units required for a correct functionality will be presented. In addition, each main unit will be briefly described.

ARINC 791 characteristic defines an airborne Very Small Aperture Terminal (VSAT), also known as an Aircraft Earth Station (AES), which uses commercial Ku or Ka-band satellite transponders [12]. Figure 2.1 illustrates the communication links between the AES and the Ground Earth Station (GES), passing through the satellite.

The main function of the satcom systems is to provide aeronautical services by transmitting, receiving and processing signals via satellite [13]. These services can be classified as safety and regularity communications or non-safety related communications. The first classification covers the communications of Air Traffic Services (ATS) and aircraft operators, known as Airline Operational Communications (AOC) which impact the air transport safety and efficiency [13]. The non-safety related communications covers private and public correspondence, such as Airline Administrative Communications (AAC) and Airline Passenger Communications (APC) [13]. These services include several applications, such as, Internet access, cellular telephony, email, and broadcast video and audio.


Figure 2.1: AES working environment [12].

To access all of these applications, it is required a group of units working together. Figure 2.2 presents a functional block diagram of the AES which illustrates all the individual units and the connections between them that need to be installed.



Figure 2.2: Ka-band system block diagram with all required units [12].

Jet Aviation not only designs the structural provisions for the satcom antenna, but also designs the installation of all the required main units. The units under Jet Aviation systems' installation design are the antenna aperture, which is part of the Outside Antenna Equipment (OAE), the Ka/Ku-band Radio Frequency Unit (KRFU) and Ka/Ku-band Aircraft Networking Data Unit (KANDU), which are part of the inside antenna equipment, and finally the Modem and Manager (MODMAN) and Aircraft Personality Module (APM), which are not part of the antenna subsystem [12]. Only the first three mentioned units compose the antenna subsystem. These units are bought from Honeywell and will be described in the next paragraphs.

• Antenna Aperture (AA)

The AA is a structure able to radiate with high gain and allows to receive and transmit ku-band or ka-band radio frequency signals [12]. There are two types of antennas depending on the type of solution which is required. The first type is used for small business jets where the antenna is installed in the tail, this is known as Tail Mounted Antenna. The second type is the Fuselage Mounted Antenna (FMA), as the name says, this antenna is installed in the fuselage and it is commonly used for air transportation aviation. In the A320 project, this is the type of antenna which will be installed since these are large aircraft. Figure 2.3 presents the antenna to be used in the project.



Figure 2.3: Honeywell's Fuselage Mounted Antenna [14].

KRFU

The Ka/Ku-band Radio Frequency Unit is the equipment which convert the signals from radio frequency (RF) to intermediate frequency (IF) and also the opposite way [12]. It receives the RF signals from the antenna and down-convert it in order to the Modman can use that signals. In the opposite way, the unit receive the IF signals from the Modman and up-convert it to RF signals in such that to it can be usable by the antenna. In addition, the KRFU also power amplifies the output signal in the up-conversion [12]. The typical installed KRFU is presented in figure 2.4.



Figure 2.4: KRFU [14].

KANDU

The Ka/Ku-band Aircraft Networking Data Unit is an equipment responsible for several functions. The first, is controlling and monitoring the antenna subsystem while providing the power to accomplish that. Secondly, the unit controls and manages the KRFU. Thirdly, it has the capability of enabling or disabling the transmission. Finally, this provides the ethernet interface between the KRFU, AA and Modman [12]. Figure 2.5 shows the Honeywell's KANDU used in the system installation.



Figure 2.5: KANDU [14].

MODMAN

The Modman is a unit composed by two sub-units: the modem and manager, where each has its own functions.

The Modem has several roles. The first is to impose the baseband data from the aircraft into a RF carrier in order to can be transmitted by the antenna subsystem. In this case, the modem is working as a modulator. In the inverse way, the modem works as a demodulator, it receives the IF signals and convert them to baseband data [12]. In addition, this sub-unit also provides real-time information to the antenna subsystem, such as signal strength [12].

On the other hand, there is the Manager which configures and commands all system components. This means that this sub-unit controls the mode of the system, where it can be found in installation, maintenance or operational [12]. Also, the manager will provide an interface between the antenna subsystem and aircraft systems.

Figure 2.6 presents the installed Modman in the project.



Figure 2.6: MODMAN [14].

APM

The Aircraft Personality Module is the unit where is stored all the information of the ka-band system configuration, which is specific for each aircraft. When the Modman needs to be changed, the APM remains and this avoids the need for a new calibration. All installation calibration parameters are still in the APM [12]. Figure 2.7 illustrates the APM used in the project.



Figure 2.7: APM modelled in $CATIA^{TM}$ [15].

2.2.2 Mechanical Interface: Antenna-Aircraft

Regarding the structural part, the charateristic ARINC 791 sets the form how antenna attaches the aircraft. This attachment is performed by seven male fittings in the fuselage with a specific position relatively to a local referential, which attach to seven female fittings in the adapter plate, where the antenna is installed [12]. The point of attachment between the male and female fittings is the reference which locates the fittings. Figure 2.8 illustrates a distribution of the seven male fittings.



Figure 2.8: Exemplification of fittings' layout.

The local referential is defined by the following manner. The plan XZ corresponds to the vertical plan of symmetry of aircraft and pass through the fitting seven. The plan XY is above of the aircraft's external skin by 8 millimeter, which corresponds to the clearance between the adapter plate and fuselage. Finally, the plan YZ pass through the fitting 3 and 4. Having the local referential defined, the standard position of each fitting is presented in table 2.1.

Fittings	X [mm]	Y [mm]	Z [mm]
1	(-635.0)	-185.5	16.8
2	(-635.0)	203.0	15.8
3	(0.0)	-392.5	-1.4
4	(0.0)	392.5	-1.4
5	(635.0)	-187.5	16.7
6	(635.0)	187.5	16.7
7	(1270.0)	0.0	28.0

Table 2.1: Fittings' coordinates [12].

The values of X in each fitting are between parenthesis because these values can vary 10 inches in the afterwards position. This is possible because the adapter plate is designed to provide 10 different positions in X direction to attach each female fitting. This adapter plate design gives the required flexibility to install the male fittings in the fuselage without these entering in clash with the OEM environment. Having these 7 points well defined, these are the starting points for all the structural design developed in Jet Aviation, beginning with the design of external male fittings. Although the detail design of the fittings is Jet Aviation responsibility, this characteristic gives some important guide lines to follow in the design process. The designed fittings are presented in chapter 3.

Fitting No	F_x [N]		F_y [N]	F_z [N]	
r itting 140.	Forward	Aft	Side (Symmetrical)	Down	Up
1	-	-	1100	400	4000
2	-	-	-	400	4000
3	1000	2300	-	2000	4500
4	1000	2300	-	2000	4500
5	-	-	1100	1000	4000
6	-	-	-	1000	4000
7	-	-	-	800	8000

Additionally, it is presented the typical interface ultimate loads that each fittings have to be able to carry without considering the bird strike loads. Table 2.2 presents these values.

Table 2.2: Typical interface ultimate fittings' Loads.

According to this standard, table 2.2 shows that each fitting must be designed only to withstand loads in specific directions. This is possible by playing with the constraints in each couple of fittings by the use of mechanisms to allow slipping in a specific axis. Furthermore, these does not experience any moment in any direction due to the installed bearing in the fittings' lug, which allow free rotation of the attachment point between male and female fitting.

2.3 Advantages of using ARINC Standard

By using this standard as background for the design brings several advantages and positive aspects to the final solution. These benefits are presented below.

- Aircraft Type and Manufacturer Interchangeability This standard is valid for all types of aircraft and independent of the manufacturer [12]. Thus, the designed solution can be adapted to any airframe, which means that there is a considerable time reduction in the conceptual design phase, since it is only necessary to adapt the solution to the new environment.
- 2. Equipment Manufacturer Interchangeability The equipments required in the installation are not exclusive, different manufacturers' equipments can fit in the standardized provisions [12]. This key reduces the probability of Jet Aviation being stuck because of the lack of equipment in its supplier's stock and can not deliver their projects in the customers' expectation time.
- 3. Frequency Band Interchangeability The same structural solution is feasible for ka-band or kuband equipment [12]. This brings increased value in terms of reliability and flexibility to the final product provided by Jet Aviation in a way that if one day the customers want to change to other frequency band, they only need to replace the equipment.
- 4. **Satellite System Interchangeability** This standard also provides flexibility regarding the satellite provider. With the same antenna subsystem, it is possible to use different satellite systems [12].

Although, the Antenna Subsystem can be reused in this situation, a new Modman should be necessary [12]. This key benefits Jet Aviation in the same way as the key mentioned in the point before.

- 5. Antenna Subsystem and Modman Interchangeability Another benefit of this standard is Antenna Subsystem and Modman can be acquired from different suppliers [12]. This is a consequence of the Satellite System Interchangeability, because in case of the Satellite provider change, the Modman needs to be changed for another, and this do not create any issue in the system functionality.
- Modman and APM Interchangeability By this standard, the Modman and APM are designed to be replaceable independently of a possible problem in some of these units. However, because of the unique signalling and protocol implementations, these two units are manufacturer-specific [12].
- 7. Mechanical interface Antenna-aircraft fully defined Using this standard, the initial design starting point for the structural part is already very well defined. With the given seven points of attachment between antenna and aircraft already defined and each maximum load that each fitting in each point can carry in each direction, the start designing process is made much more simpler. This reduces the number of engineering hours required to develop a solution from scratch and also the risk of failure.

In final, all these benefits of using this standard aim at minimizing the life cycle-costs and consequently increasing the profits of each company in the industry.

Chapter 3

Ka-band System Structural Base Design

3.1 Design's Certification Requirements

Every aircraft has a document as an identification card, which includes all information concerning the aircraft. All aircraft are only allowed to fly when they have this document. Information as general description of the aircraft, including its type and model, performance class and manufacturer, furthermore, technical characteristics and operational limitations, operating and services instructions, and operational suitability data are found there. This document is denominated as Type Certificate Data Sheet (TCDS). Additionally, it provides essential information regarding the aircraft's certification basis. This information is required in the new modifications, in order to give a base line of the requirements that are needed to show compliance.

In particular for the project, scope of this thesis, the certification basis for design change which Jet Aviation elected to comply is the EASA certification specification 25 (CS25 - large aircraft) amendment 22. In addition, compliance with the FAA certification requirements in FAR 25 amendment 1 through 145 must be also ensured. For situations where is impracticable to comply with the last certification specification, the certification basis of the TCDS - EASA IM.A.064 or FAA A28NM for the highest aircraft standards will be used [11].

The certification specification is a document composed by several paragraphs, where each paragraph gives the detailed requirement which needs to be complied. For each specific modification several paragraphs are applied and are these which constrains the design. For the modification in study in this work, specific for the designed structural provisions the paragraphs presented in table 3.1 are applied.

Paragraph	Title	Regulation	Amendment		
	Subpart C - Structure				
25.301	Loads	CS-25	22		
25.303	Factor of Safety	CS-25	22		
25.305	Strength and Deformation	CS-25	22		
25.307	Proof of Structure	CS-25	22		
25.321	Flight Loads - General	CS-25	22		
25.365	Pressurized Compartment Loads	CS-25	22		
25.561	Emergency Landing Conditions - General	CS-25	22		
	Subpart D - Design and Constructio	n			
25.613	Material Strength Properties and Design Values	CS-25	22		
25.625	Fitting Factors	CS-25	22		

Table 3.1: Certification paragraphs applicable to the structural modification [16].

Some extracts from EASA CS-25 Amendment 22 are presented [17]:

• CS 25.301 - Loads

"(a) Strength requirements are specified in terms of limit loads (the maximum loads to be expected in service) and ultimate loads (limit loads multiplied by prescribed factors of safety). Unless otherwise provided, prescribed loads are limit loads."

CS 25.303 - Factor of Safety

"Unless otherwise specified, a factor of safety of 1.5 must be applied to the prescribed limit load which are considered external loads on the structure. When loading condition is prescribed in terms of ultimate loads, a factor of safety need not be applied unless otherwise specified."

CS 25.305 - Strength and Deformation

"(a) The structure must be able to support limit loads without detrimental permanent deformation. At any load up to limit loads, the deformation may no interfere with safe operation."

"(e) The aeroplane must be designed to withstand any vibration and buffeting that might occur in any likely operating condition up to V_D/M_D , including stall and probable inadvertent excursions beyond the boundaries of the buffet onset envelope. This must be shown by analysis, flight tests, or other tests found necessary by the Agency."

CS 25.307 - Proof of Structure

"(a) Compliance with the strength and deformation requirements of this Subpart must be shown for each critical loading condition. Structural analysis may be used only if the structure conforms to that for which experience has shown this method to be reliable. In other cases, substantiating tests must be made to load levels that are sufficient to verify structural behaviour up to loads specified in CS 25.305."

• CS 25.321 - Flight Loads (General)

"(a) Flight load factors represent the ratio of the aerodynamic force component (acting normal to the assumed longitudinal axis of the aeroplane) to the weight of the aeroplane. A positive load factor is one in which the aerodynamic force acts upward with respect to the aeroplane."

"(d) The significant forces acting on the aeroplane must be placed in equilibrium in a rational or conservative manner. The linear inertia forces must be considered in equilibrium with the thrust and all aerodynamic loads, while the angular (pitching) inertia forces must be considered in equilibrium with thrust and all aerodynamic moments, including moments due to loads on components such as tail surfaces and nacelles. Critical thrust values in the range from zero to maximum continuous thrust must be considered"

CS 25.365 - Pressurized Compartment Loads

"(a) The aeroplane structure must be strong enough to withstand the flight loads combined with pressure differential loads from zero up to the maximum relief valve setting."

• CS 25.561 - Emergency Landing Conditions (General)

"(a) The aeroplane, although it may be damaged in emergency landing conditions on land or water, must be designed as prescribed in this paragraph to protect each occupant under those conditions."

CS 25.613 - Material Strength Properties and Design Values

"(a) Material strength properties must be based on enough tests of material meeting approved specifications to establish design values on a statistical basis."

CS 25.625 - Fitting Factors

"(a) For each fitting whose strength is not proven by limit and ultimate load tests in which actual stress conditions are simulated in the fitting and surrounding structures, a fitting factor of at least 1.15 must be applied to each part of -(1) The fitting; (2) The means of attachment; and (3) The bearing on the joined members."

3.2 Antenna Installation Position

Once there is an understanding about the certification requirements to have a feasible solution, the next step before starting with the detail design of the structural components, is to decide where the system will be installed. There are several possible positions, but in restricted area. This area refers to the top of the fuselage in the upper crown area in order to allow the antenna to emit to the sky. The optimum position in this area is aligned with the aircraft vertical plane of symmetry, because it is the only direction where there is a reduced anti-symmetric flow perturbation. The references for the system position are given by the aircraft longitudinal referential, along with the frame stations. Figure 3.1 presents the aircraft sections and its longitudinal referential for Airbus A319.



Figure 3.1: Airbus A319 fuselage sections and longitudinal referential [18].

The frames stations will be the references for installation localization. A feasible position rely on another variables that will be present in the following paragraphs.

Aerodynamic aircraft section

In the aerodynamic field, the aircraft can be divided in two sections. The first section goes from the nose until the end of the wings and it is classified as critical aerodynamic section [18]. This classification is explained by the fact that any perturbation of the flow in this section can have a considerable impact on airplane's performance, because this section is found before the wings and so it can influence the flow conditions before reaching the wings. The other section goes from the end of wings until the end of fuselage. This is classified as non-critical aerodynamic section. Figure 3.2 illustrates these two sections.

Between the two sections is clear that is preferable to install the system after the wings, in the non-critical aerodynamic section. However, for any given installation an aerodynamic analysis



Figure 3.2: Aircraft aerodynamic sections [19].

must be performed in order to state the aerodynamic impact of the inclusion of the antenna in the performance limitations of the airplane.

• Existing external equipment

All aircraft are equipped with several external components such as antennas and lights for navigation and anti-collision. So it is important to confirm where these equipments are in order to avoid clashes with the new system. Referring the main typical constraint external equipment are VHF (Very High Frequency), Satcom and ADF (Automatic Direction Finder) antennas and the lights of anti-collision, known as beacon light [20]. Figure 3.3 presents the external components in a green Airbus A319.



Figure 3.3: Typical external equipment in a Airbus A319 [15].

In case of an unpredicted clash with the new system, there is always a solution to solve it by relocating the existent component, as happened in the first installation with a VHF antenna in the A319.

• Inside aircraft environment

Another constraint to the placement of the antenna and all other subsystems is the environment inside of the aircraft, for example the air conditioning ducts and other systems which go along all aircraft above the ceiling and can occupy the space to install the required subsystems. It is really important to verify if there is enough space under fuselage in the area selected for the installation.

• Illumination obstruction

As it was already referred in the second point, all the aircraft have external lights. One of these lights are the anti-collision, or beacon lights which main purpose is to illuminate the airplane to be detectable by other aircraft and so avoid collisions. So, the last variable comes with the certification process, where by usage of an analysis, must prove that the new installation will not obstruct the light more than a certain limit. By this reason, there is a keep out zone which must be kept from the beacon lights to the installation in order to the modification be certifiable.

Having performed a consideration study in all these topics, the selected antenna positions are presented in table 3.2. In addiction, since the STC covers other aircraft variants, the same study was also performed for other variants. These results are presented in table 3.2.

Aircraft	FWD FRAME REF	AFT FRAME REF
A319 (Position 1)	C47	C57
A319 (Position 2)	C57	C63
A320 (Position 1)	C47	C53
A320 (Position 2)	C57	C63

Table 3.2: Reference frame stations for installation position [21].

3.3 Aircraft's Airframe Environment 3D modelling

Once the positions are selected, it is time to start preparing the 3D environment of the aircraft's primary structure. To perform this task it was used the program $CATIA^{TM}$ developed by *Dassault Systèmes*[®]. This program has several applications, such as computer-aided design (CAD), manufacturing (CAM) and engineering (CAE). In this particular task, only the CAD program capabilities were used.

From the two possible positions for the A319, the first installation was in position 1, between fuselage's frames C52-C56. In terms of mechanical engineering design, reproducing in 3D only the section between frames C52 and C56 and stringers four left (STRG4LH) to four right (STRG4RH) is enough for designing all the structural parts of the system. Yet for stress department, it is necessary to have more 3 frame bays forward and backward and two plus stringers in each side of the installation, in order to have reliable results in the structural analysis. So, finally for position 1 it is necessary to reproduce in 3D the aircraft's airframe area between frames C45 and C59 and stringers STRG6LH and 6RH. This target area is composed by two different aircraft's sections. From frame C45 to C47/51 is the central fuselage and from C47/51 to C59 is the rear fusleage. Figure 3.4 shows the complete A319's airframe 3D model of the referred target area.



Figure 3.4: Airbus A319's airframe section between frames C45 and C59 and stringers STRG6LH and 6RH, modelled in *CATIA*TM.

This task was performed with the Airbus support which shared all the manuals concerning the target aircraft models, such as Structural Repair Manuals (SRM), Illustrated Part Catalogues (IPC) and Aircraft Maintenance Manuals (AMM). Additionally, all installation, assembly and part drawings were also provided. All these materials were obtained at the Airbus's online portal named Airbus World. With these complete information, it was possible to design in detail each part of the working airplane's section.

Before presenting and describing each airframe's structural component, it is important to highlight one fact in the target environment section. In frame C47/51, there is an orbital junction, this means this area is the junction between the two aircraft's sections mentioned before. This area is specially reinforced with some specific structural components in order to give additional strength to the structure. These specific structural components will be also presented in the following paragraphs.

Firstly, the structural components from the central and rear fuselage will be presented and secondly, the orbital junction components. Regarding the two fuselage sections, the main structural components are the skin, stringers, frames and shear clips. Punctually, there may be a stringer splice section. A detailed description of each component is presented below.

Skin

The skin is a sheet metal part which covers all aircraft and gives torsional rigidity to the structure. With the technological evolution, modern aircraft tend to be more optimized in terms of reducing weight in order to achieve better performances. This optimization starts at the part level, where each part is designed to have the minimum possible weight. An example of this, is the skin of Airbus A319 which does not have an uniform thickness in the panel, it has several pockets with different thicknesses. Figure 3.5 illustrates this example, the skin panel layout with pockets detail and respective thicknesses for Airbus A319.



Figure 3.5: Skin Panel layout between frame C45 and C59 with pockets [18].

• Stringers

The stringers are a sheet metal component which goes along all the section and withstand the tension and compression loads due to the longitudinal fuselage bending. In the A319, modelled stringers have a J cross section with 0.063 inches (1.6mm) of thickness. The fuselage has a total of 44 stringers all around. The modelled stringer and respective cross section is illustrated in figure 3.6.





(a) Ten modelled stringers in context

(b) Typical stringer's cross section

Figure 3.6: Airbus A319 3D modelled stringers and respective definition.

Frames

This component is also a sheet metal part and its main function is to withstand pressure loads and give the circular shape to the fuselage. The typical frame thickness in the A319 is 0.063 inches (1.6mm). However this value can vary, depending on the frame, as an example, in the orbital junction, the frame thickness will be thicker. Figure 3.7 presents the typical frame cross section of A319.





(a) Frame C45 and C46 in context

(b) Typical frame's cross section

Figure 3.7: Airbus A319 3D modelled frames and respective definition.

• Shear Clips

The shear clips are a sheet metal part which main purpose is to spread the load between skin, frames and stringers. The typical thickness of this component in the A319 is also 0.063 inches (1.6mm). Figure 3.8 illustrates the shear clips of A319 in frame C52.



Figure 3.8: Typical Shear Clips.

Stringer Splice Sections

The stringer splice section is a machined part similar to a stringer splice, but in this case, this splice is not in a section's junction. This splice is inside of the section and its main purpose is to reinforce a specific area, where usually there are additional loads because of the installed antennas or other devices. Figure 3.9 illustrates these splices and how they fit in the stringers.



Figure 3.9: Example of a Stringer splice section in the A319.

In the junction between the two sections, the main structural components are the skin strap, stringer splices, shear clips and stabilizers. These components are described in the following paragraphs.

• Skin Strap

This component is what makes the connection between the two skin panels of the two different aircraft sections, at the same time that it gives more strength to the structure's junction point by adding more thickness in that area. Figure 3.10 illustrates how this component joins the two skin panels in the A319.



Figure 3.10: 3D modelling of the A319's skin strap in the orbital junction between central and rear fuselage.

Stringer Splices

The stringer splices are the structural components which connect the stringer of the two fuselage sections, similar to already described stringer splice section. These components are machined parts and provided the reinforcement need in the junction of the aircraft sections. The typical stringer splice in the orbital junction in consideration is illustrated in figure 3.11.



Figure 3.11: 3D modelling of the stringer splice and connection between stringers in frame C47/51 in the A319.

Orbital Shear Clips

These shear clips are different from the ones already described. In this area, there are three shear clips, one which covers the area between stringer one left-right and other two which covers the space between the other four stringers. These only attach the skin and frames. Additionally, these components are also thicker compared with the previous ones, in this section these have 2 millimeters of thickness. An illustration of the 3D modelled shear clips is shown in figure 3.12.



Figure 3.12: Orbital junction's shear clips in frame C47/51.

Stabilizers

The stabilizers are sheet metal parts which their main function is to spread the load between the frames and stringer splices in the orbital junction, by replacing the typical shear clips inside of a section. These components are placed in front of the frame and orbital junction's shear clips and forms a sheet metal sandwich with the shear clips in the middle. Figure 3.13 illustrates this description.



Figure 3.13: 3D modelling of orbital junction's stabilizers in frame C47/51.

All the connections between these structural components is performed by riveting. The main used rivet is the NAS1097DD-5. A "-5" fastener has a diameter of 5/32= 0.156 inches = 4 millimeters. This is one of the fasteners that is modelled and used in CSM study.

This process was repeated for the backward position and for the two positions in the A320.

3.4 External Supplied Components - Radome, Adapter Plate and Fairing

Not all the structural components from the system are designed in Jet Aviation. The radome, adapter plate and fairing are the three components that Jet Aviation buy from an external supplier. Carlisle is the company which provides these components. They designed a solution for these components based on the standard ARINC requirements in alignment with Jet Aviation design strategy. As an important piece of the structure of the system, these components will be presented and described one by one in the next paragraphs.

• Radome

This component can be seen from outside of the aircraft. It is installed on the top of the fuselage along with the fairing. The main function of the radome is to cover the outside antenna equipment and protect it from the external agents, such as, dirt, hail stones, water, de-icing fluid and birds [12]. The shape of the radome needs to minimize as much as possible the produced aerodynamic drag and airflow disturbances, in order to do not change considerably the aircraft performance. The radome used in Jet Aviation installation fits in any type and aircraft model is illustrated in figure 3.14.



Figure 3.14: Carlisle's radome used in Jet Aviation installation.

Adapter Plate

The adapter plate is the component that provides the mechanical interface between the radome and fairing and the Jet Aviation designed structure, by over the seven mounting lugs. Additionally, this component is the FMA base, and other components that may be installed outside. The adapter plate developed by Carlisle is interchangeable for all the different aircraft and provides several different solutions for the position of the mounting lugs, by the usage of adaptable female fittings. It allows to move few inches in the forward and backward directions of each fitting, giving the flexibility required for any installation. Figure 3.15 (a) illustrates the Carlisle's adapter plate and figure 3.15 (b) shows the detail of the adaptable female fitting.





(a) Carlisle's adapter plate used in Jet Aviation installation

(b) Adapter's Plate female fitting detail

Figure 3.15: Illustration of Carlisle's adapter plate and details.

• Fairing

From the three components, only the fairing is exclusive for each type of aircraft, in order to provide the correct interface between the radome and the aircraft's fuselage. This component is also named as skirt. Additionally, this provides the drainage required to avoid trap water and avoid corrosion [12]. Figure 3.16 illustrates a Carlisle's fairing.



Figure 3.16: Carlisle's fairing specifique for each aircraft type.

The last installation's stage is the assemblage of these three components with the Jet Aviation's internal structural provisions. Figure 3.17 presents an exploded view of these three components aligned for the installation. Moreover, it shows the FMA, the seven female fittings and the KRFU. The last component is shown as a result of a second solution for its installation, in the outside area close to the FMA. Nonetheless, for the current project different solutions were developed in order to cover the two possibilities to place the KRFU, inside or outside of the fuselage.



Figure 3.17: Exploded view of Carlisle's external equipment and outside antenna equipment [15].

3.5 Jet Aviation's Structural Provisions Design

Summarizing all the phases that have already been addressed. Firstly, it was presented the strategic background which was used as baseline for Jet Aviation ka-band satcom system solution - the Industry standard ARINC 791. Secondly, the certification requirements which the designed structural provisions must comply with were presented. Thirdly, the optimum placement of the system and active constraints were explored followed by the presentation of the structural components which composed the primary structure of the target aircraft - Airbus A319. Finally, the external structural components which make part the system but are not designed in Jet Aviation were also introduced. Now, it is only missing, the structural provisions developed by Jet Aviation, which are the most relevant content for these thesis, where a parametric optimization to the design will be performed.

The Jet Aviation's base design is composed by seven external male fittings, a general idea was already introduced in section 2.2.2 in the ARINC characteristic. Additionally, seven external doublers, mounting gussets, intercostals and frame brackets compose the complete set of the Jet Aviation's structural provisions. The external aircraft fittings are used to secure an adapter plate that support the antenna mounting plate and radome. Each fitting is attached to the aircraft external fuselage surface through a doubler. A mounting gusset is installed inside the fuselage along with each external fitting, supported by internal intercostals within the fuselage supported by the fuselage frames. The connection between these components is done by several different fasteners.

For each of these components will be explored the design process and the constraints which play an important role in the design of these components, starting from the most external component, the fittings and ends in the frame bracket. All of these components are sized and analysed under several failures modes that are identified and checked for structural integrity. Figure 3.18 illustrates the complete assembly of Jet Aviation's design and the numbering for each groups of components for identification purposes.



(a) Jet Aviation strutural provisions 3D model installed in the upper lobe fuselage



(b) Jet Aviation strutural provisions 3D model in $CATIA^{TM}$ with the respective numbering of each groups of components

Figure 3.18: Jet Aviation structural provisions' solution.

• Fittings

The fittings are an assembly of a machined part made from aluminium plate with a bearing which make the connection between the aircraft's primary structure and the adapter plate. These must be designed to transfer the flight, decompression and inertial loads to the aircraft airframe [22]. ARINC 791 sets several constraints to the design of these parts, as example the reserved area for each fitting and also the respective thickness in the lug. To size and justify the strength of the fitting the failure modes presented in the table of figure 3.19 were consider. In addiction, figure 3.19 presents the 3D modelled fittings of the ka-band satcom system for the A320 family.

Analysis Location	Failure Mode		
	Ultimate and yielding tensile strength		
Lug	Ultimate and yielding bearing		
	Shear-out		
Pin Shear and bending			
Eitting Strongth	Tensile strength		
Fitting Strength	Von Mises		
Fitting base	Ultimate and yielding bearing		
Fasteners	Shear and tension strength		



Figure 3.19: Table with failure modes considered for the fitting design [22]. Illustration 3D model of all the fittings in context.

External Doublers

The external doublers are sheet metal parts made from aluminium clad which reinforce the area where the fittings are placed with a purpose to replace the stiffness lost due to the installation of the fittings and connectors. In addition, the doubler supports the load transfer from the fittings to the aircraft pressure vessel. The failure modes considered to size and justify the strength of the

Analysis Location	Failure Mode
Doubler bearing	Ultimate and yielding bearing
Fasteners	Shear and tension strength



Figure 3.20: Table with failure modes considered for the doublers design [22]. Illustration 3D model of all doublers in context.

doublers is presented in the table of the figure 3.20, with aside illustration of the 3D model of all doublers in context.

Mounting Gussets

The Mounting Gussets are machined parts made from aluminium plate with the main function of transferring the loads from the fittings to the intercostals. The failure modes which drove the design of these parts are presented in the table of the figure 3.21. In addition, an illustration of the 3D modelled mounting gussets is also presented.



Figure 3.21: Table with Failure modes considered for the gussets design [22]. Illustration 3D model of the typical mounting gusset.

• Intercostals and Frame Brackets

The intercostals are sheet metal parts made from aluminium clad. The frame brackets are machined profiles made from aluminium plate. The main function of these two components is to transfer the load. Firstly, the loads are transferred from the mounting gussets to the intercostals and secondly, from the intercostal to the frame bracket which finally transfer to the aircraft's primary structure, more specific to the frames. In order to size these components the failure modes presented in table 3.3 were taking into account. Figure 3.22 illustrates the 3D modelled intercostals plus the frame brackets.

Analysis Location	Failure Mode		
Junction with Gusset	Bearing analysis		
	Maximum tensile stress		
Intercostal	Maximum shear load		
	Von Mises (Shear plus tensile stress combination)		
Juntion with Frame Brackets	Bearing analysis		

Table 3.3: Table with Failure modes considered for the intercostals and frame brackets design [22].





The design solution presented was developed with the purpose of be reusable in several aircraft of the A320 family, therefore is valid for all the proposed aircraft type, A319 and A320 series.

Chapter 4

Parametric Optimization

In chapter 4, an implementation of a parametric optimization is presented. This focus on the structural properties of the provisions designed by Jet Aviation which were already presented in section 3.5. To perform this optimization, seven different hypotheses are defined, and using the Jet Aviation provisions as the initial solution and the results obtained from static structural and fatigue analysis for the different hypothesis, a study is conducted to confirm which solution presents better results in terms of weight reduction and fatigue lifetime comparing to the initial solution for the critical load case.

4.1 Hypotheses

The seven hypotheses in study are a combination of three structural modifications in three components of the initial design. The components which were found interesting to the modify are the external fittings, the doublers and intercostals. These three modifications will explained in more detail, along with the reason behind this choice in the following paragraphs, starting with fittings.

1. Change - Fitting (F) - The external fitting is a structural component which is constrained since the beginning by the ARINC Standard, which set a minimum thickness for the lug of 0.346 inches (8.8mm) as it is introduced in section 3.5. An opportunity to optimize the fittings can be achieved by reducing its overall thickness from 0.346 to 0.189 inches (4.4mm), but keeping constant the thickness in the lug. Moreover, reducing the thickness in the fitting base to 0.197 inches (5mm) without changing the fitting's height. This hypothesis can be interesting to study, in order to reduce the overall installation's weight without having a huge impact on the fatigue life's value. Figure 4.1 illustrates the differences between the initial design fitting one and the same modified, as example of the modification performed in all the fittings.



(a) Initial design fitting 1



(b) Modified fitting 1

Figure 4.1: Modified versus initial design fitting one.

2. Change - Doublers (D) - In Jet Aviation, the doublers are designed following a "repair" logic given by the SRM, which states that the external doubler must be 0.008 inches (0.2 mm) thicker than the skin in touch [18]. In contrast to this methodology, it will be used the "new design" logic where it will be studied and justified the case where the doubler's thickness will be set to the same of the skin. Table 4.1 presents the initial design value and the modified one for the doublers' thickness.

Doubler Thickness [in]			
Initial doublers	0.071		
Modified doublers	0.063		

Table 4.1: Doubler's thickness of the initial design and the modified.

3. Change - Intercostal (I) - Before starting the A320 family project, it was developed the solution for the Boeing Business Jet 737 family. In that solution the intercostals have a thickness of 0.08 inches (2mm) whereas in the current project the intercostals have a thickness of 0.1 inches (2.54mm). It is intend to study the usage of intercostals with the same thickness of the versions used on Boeing 737 solution. Table 4.2 summarize the information in consideration for this study.

Intercostal Thickness [in]			
Initial Design	0.1		
Case Study (B737 Family Solution)	0.08		

Table 4.2: Intercostals' thickness of the initial design and the modified.

From now on, the three changes are denominated as F,D and I referring the modifications on the **F**ittings, **D**oublers and **I**ntercostals to be more clear the different hypotheses in study. Table 4.3 presents the complete set of hypotheses proposed for the study.

Design Hypothesis				
1	F			
2	D			
3	I			
4	F+D			
5	F+I			
6	D+I			
7	F+D+I			

Table 4.3: Definition of the seven hypothesis for the study.

4.2 Load Cases

Before introducing the set of loads which the installation will be subjected during its function, it is necessary to define the referential of the coordinate system and the signs convention. Figure 4.2 illustrates the reference aircraft coordinate system and sign convention used in the analysis. In addition, since the analysis for the base design were performed in imperial units, all the analysis in this study will be performed in same unit system. Figure 4.2 also shows the typical units for the used entities in imperial system.



Figure 4.2: Coordinate system used entities in the analysis [16]. Typical units used entities in the analysis.

Several load cases (L/Cs) need to be set in order to simulate the different conditions which the aircraft can experience during its life. The load cases identified represent real situations such as gust, fatigue or crash loads, for which must be proved that designed antenna's structure can withstand these loads without a catastrophic failure such that it can be approved by a certification authority. Table 4.4 presents the load cases used in the initial design.

As table 4.4 shows, each load case is a combination of the inertia of the designed structural provision plus the equipments, the bending and shearing of the fuselage barrel in the target section and the

L/Cs	Name	Inertia of External Equipment	Bending & Shear Fuselage	Cabin Pressure	Radome	Condition
1	Radome rapid decompression	1.0g Down	1.0g Down	DP = 8.99 psi Operating Pressure	3 Psi Radome Over Pressure + CFD Cruise Load Case	Failure Load
2	Fuselage Burst Pressure	_	—	DP = 9.74 x 1.33 x 1.5 = 19.43 psi Max relief valve	_	Failure Load
3	Max Vertical Gust Down	3.2g x 1.5 = 4.8g Down	3.2g x 1.5 = 4.8g Down	DP = 9.74 x 1.5 = 14.61 psi Max relief valve	1.5 X CFD Critical Longitudinal	Ultimate Load
4	Max Vertical Gust Up	2.5 x 1.5 = 3.75g Up	2.5 x 1.5 = 3.75g Up	DP = 9.74 x 1.5 = 14.61 psi Max relief valve	1.5 X CFD Critical Longitudinal	Ultimate Load
5	Critical Maneuver Down	2.5 x 1.5 = 3.75g Down	2.5 x 1.5 = 3.75g Down	DP = 9.74 x 1.5 = 14.61 psi Max relief valve	1.5 X CFD Critical Longitudinal	Ultimate Load
6	Critical Maneuver Up	1 x 1.5 = 1.5g Up	1 x 1.5 = 1.5g Up	DP = 9.74 x 1.5 = 14.61 psi Max relief valve	1.5 X CFD Critical Longitudinal	Ultimate Load
7	Crash Load Forward	9g Fwd	_	_	_	Ultimate Load
8	Crash Load Down	8.6g Down	—	_	_	Ultimate Load
9	Crash Load Side	3g Side	—	_	—	Ultimate Load
10	Crash Load Backward	1.5g Backward	_	_	_	Ultimate Load
11	Critical Aerodynamic Sideslip	1.0 x 1.5 = 1.5g Down	1.0 x 1.5 = 1.5g Down	DP = 9.74 x 1.5 = 14.61 psi Max relief valve	1.5 x CFD Critical Sideslip	Ultimate Load
12	Fail Safe (Loss of Fitting)	1.0g Down	1.0g Down	DP = 8.99 psi Operating Pressure	CFD Cruise Load Case	Failure Load
13	Fatigue Load	1.3g Down	1.3g Down	DP = 8.99 psi Operating Pressure	CFD Cruise Load Case	Fatigue Load

Table 4.4: Load cases extracted from [16].

aerodynamic and pressurization loads. The cabin operating pressure are extracted from [23]. The applicable gust loads are therefore derived from the flight loads envelope.

In terms of the bending and shearing of the fuselage barrel, it was considered for the analysis the highest value of bending moment and shear load presented between the aircraft types being covered in

the several installation positions, in order to analyse the critical condition and so the other possibilities are covered by this analysis. Therefore, all the different installations are substantiated by the same analysis.

- Load case 1 simulates an ultimate decompression condition, with a very conservative value of
 pressure for the maximum differential pressure between the radome and the external environment.
 This failure load is combined with the operating load conditions of the aircraft: 1g inertia and
 fuselage loads, aerodynamic cruise loads, normal cabin operating pressure. The aerodynamic
 loads are extracted from the Computational Fluid Dynamics (CFD) analyses performed by the
 stress department.
- Load case 2 simulates the cabin burst pressure condition. This failure load case is needed to show compliance with two extra paragraphs: 25.365(d) and 25.303. The paragraph 25.365 defines the pressurized structure limit load as 1.33 times the maximum relief valve setting. This must be multiplied by 1.5 as by paragraph 25.303 to obtain the corresponding ultimate load condition.
- Load cases 3 through 6 represent the critical manoeuvrer and gust conditions. The gust loads factors are extracted from [23] Airbus flight loads envelopes.
- There are more three crash load cases, but these are not consider because they are already covered by Load Cases 8, 9 and 10. These cover the crash Load cases 6*g* down, 3*g* side and 1.5*g* backward.
- Load cases 7 to 10 are crash load cases.

For this parametric optimization the first four load cases are the critical ones, however, it is only used the load case number 1, radome rapid decompression load, which can be assumed as a good approximation of the most critical load case. In addiction, for the fatigue analysis the load case 13, the fatigue load, is used.

4.3 Methodologies

To conduct the parametric optimization, two types of analyses were performed. Firstly, a static structural analysis to verify the new safety margins of the modified parts and confirm the reliability of the overall installation after the modification. The second, a fatigue analysis which aims at calculating the new fatigue life for the seven different hypotheses. For the two analyses the engineering software *FEMAP* developed by *Siemens PLM Software* was used to build the finite element model, execute the simulations and present the post-processing results. This model was built by the stress department with the support of mechanical side which prepare all the geometries for the model, where I actively contribute. The complete description of this model is presented in [16]. All the steps executed in the two analyses are presented in the following paragraphs.

4.3.1 Static Structural Analysis

This analysis is focused on the components which were modified, therefore only the equations used to verify the strength of them are presented. For the remain installation's and fuselage airframe's components their structural integrity after the modifications was verified. The only information which will appear regarding the last components will be in chapter 5, in the results, stating if they are still strength enough or not, and for a negative result, which component needs to be resized.

The first step to perform the analysis was to run the static analysis of the model in *FEMAP* for the load case one for each of the seven hypotheses in order to extract the reaction loads on the fittings' lug. Figure 4.3 presents the applied loads in the seven fittings for the initial design for the load case one.





For each modified component is presented the failure modes verified, followed by the respective equations to obtain the safety margins.

- 1. Fitting The first component is the fitting where it is analysed the lug, the fitting strength, the base bearing and von mises stress.
 - Lug Analysis

The methodology used for the analysis is the standard aerospace one, under axial and transversal loads, given by [24].

Under axial loads, the lug must be sized for the following failure modes: Shear-bearing failure (shear out), ultimate and yield tensile failure. Figure 4.4 (a) illustrates the studied failure modes. Figure 4.4 (b) presents the lug's dimensions, where W is the lug gross width, D is the lug internal diameter, a is the lug edge distance and t is the lug thickness.



Figure 4.4: Lug details for axial loading.

The projected bearing area is $A_{BR} = D \times t$ and the tensile net section is $A_T = (W-D) \times t$.

Shear-Bearing allowable is calculated as per equation 4.1.

$$P_{bru} = k_{br} \times F_{TU,X} \times A_{BR} \tag{4.1}$$

 P_{bru} is the ultimate load for shear-out and bearing failure, k_{br} is the shear-bearing efficiency factor given in [24], and $F_{TU,X}$ is the ultimate tensile stress in x-direction of the lug material. All the graphics to obtain the factors as k_{br} can be found in annex A.

Finally, the **shear-bearing margin of safety** is calculated by equation 4.2.

$$MS_{LUG,BRU} = \frac{P_{bru}}{FF \times P} - 1 \tag{4.2}$$

P is the ultimate pure axial load applied and FF is the fitting factor 1.15 as required per paragraph 25.625.

Tension Allowable is calculated as per equation 4.3:

$$P_{TU} = k_t \times F_{TU,X} \times A_T \tag{4.3}$$

 P_{TU} is the ultimate load for tensile failure, k_t is the tensile efficiency factor given in [24], and $F_{TU,X}$ is the ultimate tensile stress in x-direction of the lug material.

Finally, the Tension Margin of safety is calculated by equation 4.4.

$$MS_{LUG,TU} = \frac{P_{TU}}{FF \times P} - 1 \tag{4.4}$$

P is the ultimate pure axial load applied and FF is the fitting factor 1.15 as required per paragraph 25.625.

Yield failure allowable is calculated as per equation 4.5.

$$P_{TY,X} = C \times \left(\frac{F_{TY,X}}{F_{TU,X}}\right) \times P_{U,MIN}$$
(4.5)

 $P_{TY,X}$ is the yield load, *C* is the yield factor given in [24], $F_{TY,X}$ is the ultimate tensile stress in x-direction of the lug material and $P_{U,MIN}$ is the minimum between P_{TU} and P_{BRU} . Finally, the **Yield Margin of safety** is calculated by equation 4.6.

 $MS_{LUG,Y} = \frac{P_{TY,X}}{FF \times P_Y} - 1 \tag{4.6}$

 P_Y is the limit pure axial load applied and FF is the fitting factor 1.15 as required per paragraph 25.625.

Under transversal loads, the lug must be sized again for the same failure modes as in axial loading: Ultimate and yield tensile and shear-bearing failure. Figure 4.5 (a) illustrates the studied failure modes.



(a) Failures under transversal loading

(b) Lug Geometric Characteristics

Figure 4.5: Lug details for transversal loading.

Figure 4.5 (b) presents the lug's dimensions, where A_1 and A_4 are $A_1 = A_4 = \frac{t}{2} \times (W - \frac{D}{\sqrt{2}})$, A_2 is $A_2 = \frac{t}{2} \times (W - D)$, A_3 is the least area on any radial section around the hole $A_3 = \frac{t}{2} \times (2 \times a - D)$.

The average area is $A_{AVG} = \frac{6}{\frac{3}{A_1} + \frac{1}{A_2} + \frac{1}{A_3} + \frac{1}{A_4}}$ and the projected bearing area is $A_{BR} = D \times t$.

Tension Allowable is calculated as per equation 4.7.

$$P_{TRU} = k_{tru} \times F_{TU,Y} \times A_{BR} \tag{4.7}$$

 P_{TRU} is the ultimate load for tensile failure under transversal loads, k_{tru} is the tensile efficiency factor for transversal loads given in [24], and $F_{TU,Y}$ is the ultimate tensile stress in transverse direction of the lug material.

Finally, the Tension Margin of safety is calculated by equation 4.8.

$$MS_{LUG,TU} = \frac{P_{TRU}}{FF \times P} - 1 \tag{4.8}$$

P is the ultimate pure transversal load applied and FF is the fitting factor 1.15 as required per paragraph 25.625.

Yield failure allowable is calculated as per equation 4.9.

$$P_{TY,Y} = k_{try} \times F_{TY,Y} \times A_{BR} \tag{4.9}$$

 $P_{TY,Y}$ is the yield load, k_{try} is the tensile efficiency factor for transversal loads given in [24] and $F_{TY,Y}$ is the tensile yield strength in transverse direction of the lug material.

Finally, the **Yield Margin of safety** is calculated by equation 4.10.

$$MS_{LUG,Y} = \frac{P_{TY,Y}}{FF \times P_{TY}} - 1$$
(4.10)

 P_{TY} is the limit pure transverse load applied and *FF* is the fitting factor 1.15 as required per paragraph 25.625.

• Fitting Strength

To evaluate the fitting strength an analysis of fitting unfolding under the applied loads is performed. Due to the tensile loads applied on the lug, the fitting will experience bending stresses. It is assumed that the fitting base is clamped in the fastener axis. For the analysis description is consider the general situation where fitting loading is decomposed in X/Y and Z direction. Since there are several fasteners, the effective length for bending can not overlapping, therefore, L_{eff} maximum is equal to the pitch on the central fastener and half the pitch plus the edge distance on the side ones. Figures 4.6 illustrate the free body diagram of the analysis and a section view of a fitting with an angle.

The first step is to calculate the loads at each fastener location and evaluate the most critical location. To achieve this, the shear, tension loads and moment due to the shear load reacted on the base must be calculated after projection of the tension loads into the base axis reference system. It is consider all the load is transferred in tension due to the high angle of the fitting.

Regarding the tension load, the load value of each row of fasteners will carry is given by a sum of moments with center in one of the fasteners axis. Figure 4.7 presents the FBD with the required dimensions. So, the tension loads for each row of fasteners is given by equation 4.11.





(a) Typical Free body diagram of a straight fitting [22]

(b) Section view of a fitting with an angle [22]

Figure 4.6: Illustration of Fitting' FBD and with an angle.

$$T_{L-FAST} = T \times \frac{d_b}{b_B} = -R_{L-FAST} \qquad T_{R-FAST} = T - T_{L-FAST} = -R_{R-FAST}$$
(4.11)



Figure 4.7: Fitting's FBD to calculate tension load on each row of fastners due to the tension load applied in the lug [22].

Regarding the moment produced by the shear load on the lug, the tension load value of each column of fasteners will carry is given by equation 4.12. The central support is not taking any loads, only the edge fasteners react to all the moment. Figure 4.8 illustrates the FBD with the required dimensions.

$$T_M = \frac{M}{L_B/2} \tag{4.12}$$

Regarding the applied shear load, the load which is reacted by each fastener in shear is given by equation 4.13. In addition, the tension load that each fastener reacts is given by equation 4.14, where *n* is the number of fasteners attaching the fitting.

$$S_{FAST} = \frac{S}{n} \tag{4.13}$$

$$T_{FAST} = \frac{T_{LorR-FAST}}{n/2} \tag{4.14}$$



Figure 4.8: Fitting's FBD to calculate tension load on each row of fastners due to the moment [22].

Finally, it is possible to calculate the bending and shear strength and von mises stresses and respective margins of safety by the fitting unfolding method. Therefore, the bending strength stress and safety margin are calculated by equation 4.15 and 4.16, respectively, where *P* is the critical tension load reacted by the fasteners, *L* is the base length, *t* is the base thickness, $\delta = L - t$, $L_{eff} = min[L; b_1] + min[L; b_2]$ and F_{TU} is the ultimate stress for tensile failure. Figure 4.9 illustrates the required dimensions for the calculation of the method.



Figure 4.9: Fitting unfolding method illustration of required dimensions [22].

$$f_{FLG-BEND} = \frac{12 \times P \times a^2 \times (\delta - a)^2}{\delta^3 \times L_{eff} \times t^2}$$
(4.15)

$$MS_{FLG-BEND} = \frac{F_{TU}}{FF \times f_{FLG-BEND}} - 1$$
(4.16)

The shear strength stress of the fitting and its safety margin are calculated by equation 4.17 and 4.18, respectively. Where S_T is the sum of the base shear plus the shear produced the tension load when the fitting has an angle, $A_{SHR} = L_B \times t$ and F_{SU} is the ultimate stress for shear failure.

$$f_{SHR} = \frac{S_T}{A_{SHR}} \tag{4.17}$$

$$MS_S = \frac{F_{SU}}{FF \times f_{SHR}} - 1 \tag{4.18}$$

The von mises stress is a combination of the bending plus the shear stresses. This is calculated by equation 4.19 and the respective safety margin by equation 4.20.

$$f_{VM} = \sqrt{f_{FLG-BEND}^2 + 3 \times f_{SHR}^2}$$
 (4.19)

$$MS_{VM} = \frac{F_{TU}}{FF \times f_{VM}} - 1 \tag{4.20}$$

• Fitting Base Bearing

Once the shear load applied to the fasteners is calculated, it is possible to determinate the margin of safety under bearing for the fitting base for the ultimate and yield cases by equations 4.21 and 4.22, respectively, where, MS_{BRU} and MS_{BRY} are the ultimate and yield bearing Margin of Safety, respectively, D_{FAST} is the diameter of the fastener hole, t is the thickness of the fitting base, FF is the fitting factor: 1.15 as per paragraph 25.625 and finally $S_{FAST,U}$ and $S_{FAST,L}$ are the ultimate and limit applied shear load at each fastener, respectively.

$$MS_{BRU} = \frac{F_{BRU} \times D_{FAST} \times t}{FF \times S_{FAST,U}} - 1$$
(4.21)

$$MS_{BRY} = \frac{F_{BRY} \times D_{FAST} \times t}{FF \times S_{FAST,L}} - 1$$
(4.22)

• Von Mises Stress

Additionally, it was computed the critical von mises stress for the seven fittings to verify their strength after the optimization pockets and check if there is no stess concentration in the area around the lug. To perform this, it is used the post processing of the analysis run in *FEMAP* to find the critical element with the highest von mises stress. The allowable of the material in LT direction is extracted from the literature [25] and the safety margin can be calculated by equation 4.23.

$$MS_{VM} = \frac{F_{VM}}{FF \times f_{VM}} - 1 \tag{4.23}$$

- 2. External Doublers Secondly, the doublers are analysed in bearing and von mises stress.
 - Bearing

To verify the doubler's strength in bearing, firstly, it is used the post processing of the analysis run in *FEMAP* to find the critical element with the highest shear load. Secondly, it is calculated by equation 4.24 the bearing allowable of the doubler counting with a 20% abatment for the wet fasteners. Where S_{BRU} is the ultimate bearing strength stress, *t* is the doubler thickness and *D* is the diameter of the critical hole in the doubler.
$$P_{BRU} = S_{BRU} \times t \times D \times 0.8 \tag{4.24}$$

Finally, the safety margin can be calculated by equation 4.25, where S is the shear load in the critical element in the doubler.

$$MS_{BRU} = \frac{P_{BRU}}{FF \times S} - 1 \tag{4.25}$$

Von Mises Stress

To verify the doubler's strength in terms of von mises, it is used again the post processing of the analysis run in *FEMAP* to find the critical element with the highest von mises stress. The allowable of the material in LT direction is extracted from the literature and the safety margin can be calculated by equation 4.26.

$$MS_{VM} = \frac{F_{VM}}{FF \times f_{VM}} - 1 \tag{4.26}$$

 Intercostals - Thirdly, the intercostals are analysed under the following failures modes: Bearing analysis of the gusset intercostal junction and I-bracket junction; maximum tensile and compressive stress on the outer and inner flange; maximum shear load in the intercostal's web; and von mises stress.

· Bearing Analysis

The analysis' procedure performed in the gusset intercostal and intercostal I-bracket junctions for the bearing is the same already presented for the fitting base.

· Maximum tensile and compressive stress on the outer and inner flange

The intercostal can me modelled as beam simply supported in the edges where is working under the shear load transferred through the attachments in the gusset wall, the bending moment in Y direction of aircraft axis due to this load and the extra bending moment due to the eccentricity of the same load. The intercostal is supported by the frames through two I-brackets attachments in the edges. The reactions in these attachments are calculated with a sum of moments expressed in equation 4.27. With the reactions computed, it was possible to evaluate the associated and eccentricity bending moments with equations 4.28 and 4.29, respectively.

$$R_A = \frac{P \times L_1}{L} \qquad \qquad R_B = \frac{P \times (L - L_1)}{L} \qquad (4.27)$$

$$M_y = R_A \times (L - L_1) = R_B \times L_1 \tag{4.28}$$

$$M_z = R_B \times L_1 \times \frac{e_{END-PAD}}{h_1} \tag{4.29}$$

Where the dimensions required are illustrated in figures 4.10 (a) and (b).



(a) Intercostal side view with applied load and respective reactions on edges [22]



Figure 4.10: Illustration of intercostals' FBD.

Once the moments are computed, the stresses in the intercostal are evaluated by applying Hooke's law for unsymmetrical sections which is traduced by equation 4.30. Figure 4.11 illustrates the cross section of one of the intercostals and the points in each section corner where will occur the maximum tension and compression stresses, therefore are evaluated there. Thus, the bending is reacted by the inner and the outer flanges of the intercostal.



Figure 4.11: Intercostal cross section with neutral axis [22].

$$f_{i} = \frac{-(M_{Y} \times I_{ZZ} + M_{Z} \times I_{YZ}) \times d_{Z^{i}} + (M_{Z} \times I_{YY} + M_{Y} \times I_{YZ}) \times d_{Y^{i}})}{I_{YY} \times I_{ZZ} - I_{YZ}^{2}}$$
(4.30)

Where, I_{YY} , I_{ZZ} and I_{YZ} are the cross section moments of inertia in the different directions and d_{Y^i} and d_{Z^i} are the coordinates of each point in the intercostal.

Finally, the safety margins of the tensile and compressive strength are computed by equations 4.31 and 4.32, respectively.

$$MS_{T-INTERCOSTAL} = \frac{F_{TU}}{f_T} - 1$$
(4.31)

$$MS_{C-INTERCOSTAL} = \frac{F_{CY}}{f_C} - 1$$
(4.32)

Where, F_{TU} , F_{CY} are the ultimate stresses of the material for the respective modes, tensile and compressive.

· Maximum shear load in the intercostal's web

To verify the intercostal's web shear strength it is calculated the maximum shear load applied on it by equation 4.33 and, finally the safety margin by equation 4.34.

$$S_{MAX} = \frac{3}{2} \times S \tag{4.33}$$

$$MS_S = \frac{F_{SU}}{S_{MAX}} - 1 \tag{4.34}$$

Von mises stress

The analysis' procedure for the von mises stress in the intercostal is the same one already used for the fittings and doublers.

4.3.2 Fatigue Analysis

The fatigue analysis is performed in order to justify that the fatigue life is not a limiting factor for the threshold inspection. Due to the highest load condition, the doublers are the critical components which must be subjected to the study. In addiction, also the fatigue life of the modified fittings is studied in order to compare with fatigue life of the initial fittings. The analysis is based on the material Wohler curves or stress-life curves (S-N), which relates the maximum stress with the fatigue life, in cycles. The definition of one cycle is presented in the following section. Figure 4.12 presents the S-N curves for the doublers material, the 2024-T3 aluminium alloy.



Figure 4.12: S-N curves and correlations for 2024-T3 aluminium alloy [25].

To extract the fatigue life from figure 4.12, firstly is necessary to compute the stress concentration factor which is estimated by the theory of severity factor (SF) [22]. This theory is used to evaluate the peak stress distribution in the fastened area. This formula only take into consideration the structural configuration, and not the effect of the material quality or the stress level. Equation 4.35 presents the severity factor definition [24].

$$SF = \left(\frac{\alpha \times \beta}{f_{ref}}\right) \times \left[\left(\frac{K_{tb} \times \Delta P}{D \times t}\right)\theta + \left(\frac{K_{tg} \times P}{W \times t}\right)\right]$$
(4.35)

Where, α and β are parameters related to the hole, K_{tb} and K_{tg} are the stress concentration factor referred to nominal bearing stress and gross area stress and θ is the bearing distribution factor. These parameters are extracted from the literature [24]. Regarding the last three parameters, the values are extracted from graphics which are presented in the annex A. In addiction, W and t are the plate width and thickness, respectively, and D is the hole diameter. Finally, ΔP is the load transferred by the fastener, which is extracted from the static load case, P is the by-pass load which is computed by equation 4.36 and f_{ref} is the nominal stress in the doubler between the critical rivets.

$$P = (W \times t \times f_{ref}) - \Delta P \tag{4.36}$$

To compute f_{ref} , it is build a small FEM model, with a fraction of the skin with the critical doubler with all the rivet holes. The critical doubler is identified by the static analysis which determine the doubler two as the most loaded component, so the skin section around this component is modelled. Figure 4.13 presents the FEM model produced by Jet Aviation for the fatigue analysis.



Figure 4.13: Fatigue FEM model with loads [26].

The applied loads in the model are extracted from the static analysis for the seven configurations and

are applied in a distributed way, lbf per in [lbf/in], in the boundaries. The loads are composed by longitudinal and circumferential loads, in X and Y direction, respectively. Once, the analysis is completed it is possible to extract the required value f_{ref} by identifying the critical fastener row. Figure 4.14 illustrates the post processing of the analysis for the major principal stress.



Figure 4.14: Major Principal Stress results of the FEM model [26].

Once, all the required parameters are calculated, it is possible to determinate the Fatigue Quality Index with equation 4.37, which is similar to the stress concentration factor, assuming a discrepancy factor of 1.2 by [24]. Followed by the local stress concentration factor computed by equation 4.38 [27]. And, the net section stress by equation 4.39.

$$K = 1.2 \times SF = K_t \tag{4.37}$$

$$K_{tn} = K_t \times \frac{(W - D)}{W} \tag{4.38}$$

$$f_{net} = f_{ref} \times \frac{(W)}{W - D} \tag{4.39}$$

Finally, it is computed the equivalent stress by equation 4.40 to determine the number of cycles of fatigue life using equation 4.41.

$$S_{eq} = S_{max} = f_{net} \times \left(\frac{K_{tn}}{K_t}\right) \tag{4.40}$$

$$LogN_f = 8.3 - 3.3 log(S_{eq} - 8.5) \tag{4.41}$$

Applying the scatter factor of 5, it is obtained the final result of the number of cycles as per equation 4.42. The scatter factor of 5 is the typical value used for damage tolerance structures by OEMs [26].

$$N_f^* = N_f/5$$
 (4.42)

For the fittings case, it is extracted from the FEM model the maximum and nominal stresses and the stress concentration factor K_t is calculated. Once the K_t is computed, is used the already described methodology to find out the number of cycles of fatigue life, N_f^* of the modified fittings.

Spectrum assumption

For this analysis is assumed that one cycle is equivalent to one flight. By the reason that, a conservative once-per-flight constant amplitude Ground-Air-Ground (GAG) loading cycle has been considered instead of a more complex flight-by-flight loading spectrum, based on [28].

To perform this analysis, the required geometry dimensions of the fittings and intercostals are extracted from the 3D model and summarized in figures A.1 and A.2 which are included in the appendix A of this document.

Chapter 5

Results

Several results were obtained from this study. Firstly, it is presented the obtained results in terms of weight of the several hypotheses. Secondly, the results of the static analysis are shown. Thirdly, the fatigue life cycles of the modified components are presented as part of the fatigue analysis results. Finally, a combination of all the results are performed to find out the optimal hypotheses.

5.1 Weight

Regarding the weight results, with the modification performed in the fittings, doublers and intercostals to define the seven design hypotheses as a combination of these three changes, the weight reduction flow with all the hypotheses in relation with the initial design is presented in figure 5.1.



Figure 5.1: Percentage of weight reduction of initial Jet Aviation provisions.

Hyphothesis ID	1	2	3	4	5	6	7
Weight Reduction [%]	1.26	1.00	8.16	2.26	9.42	9.15	10.42

Table 5.1: Values of weight reduction percentage for the seven hypotheses.

The results presented in table 5.1 show that hypothesis number seven, which includes the three modified components, presents the highest weight reduction, a reduction of 10.4% of the total weight

of the initial design. In addition, it also shows that the modified component with the larger impact on the weight reduction is the intercostals, due to the large number of times that this component is used and also, due to its considerable initial weight compared to the other two modified parts. Following the same logic, accounting only with two modified components, the hypothesis with the greater result is the hypothesis number five, which combines the modified intercostals with the modified fittings, which are the second component with more impact in the weight reduction.

To sum up, the hypothesis number seven is the lightest design from all the hypotheses. The static analysis results will confirm if the structural configuration of this hypothesis maintains the structural integrity by continuing to have positive safety margins in all the design components.

5.2 Static

The goal of the static analysis is to obtain results which confirm that each of the studied hypotheses maintain the structural integrity. This was performed in two steps, already described in section 4.3.1. From the first step, graphics in figure 5.2 present the extracted values of the reactions of all the fittings in the respective directions for all the hypothesis.



((a)) Fittings reactions in X direction





((c)) Fittings reactions in Z direction

Figure 5.2: Fittings reactions for the seven hypothesis

Remembering what was stated in section 2.2.2, the fittings are designed only to sustain loads in specific directions. Figure 5.2 confirms that, for instance, loads in direction X and Y are only carried

by fittings three and four and one and five, respectively. Furthermore, all the fittings carry loads in Z direction as it is possible to check in graph 5.2 (c). In terms of obtained results, it shows that for all the configurations the reactions in the fittings are almost similar. Comparing the reactions from the seven hypotheses against the reactions of the initial design, it shows that the reactions suffer short alterations, at units scale, as it is possible to confirm with nearly horizontal lines in the graphs (a),(b) and(c) of figure 5.2. These results show that the geometry modifications performed in the selected parts had an insignificant impact on the global structural system's rigidity, what explains the shorts changes in the reactions.

In the second step, using the methodology described in section 4.3.1, the safety margins were computed for all the modified parts for the specified failures modes of all the hypotheses. Firstly, it is presented the fitting results, from fitting one to seven (tables 5.2 to 5.8).

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}$ =	273.99	277.65	277.65	301.72	288.53	313.5	306.16	317.99
$MS_{LUG,TU}$ =	404.17	428.48	409.57	445.03	445.25	483.74	451.58	490.65
$MS_{LUG,Y}=$	273.99	277.65	277.65	301.72	288.53	313.5	306.16	317.99
Transversal load:								
$MS_{LUG,TRU}$ =	6.30	6.29	6.29	6.35	6.23	6.29	6.33	6.28
$MS_{LUG,TY}=$	10.92	10.90	10.90	10.99	10.81	10.91	10.97	10.88
Fitting Strength								
$MS_{FLG-BEND}$ =	8.60	5.32	8.58	8.65	5.27	5.32	8.63	5.31
$MS_{FLG-SHR}$ =	897.29	909.25	909.25	987.88	944.81	1026.38	1002.40	1041.02
MS_{FLG-VM} =	8.60	5.32	8.58	8.65	5.27	5.32	8.63	5.31
Fitting Base								
Bearing								
MS_{BRU} =	1111.17	914.65	1125.98	1223.33	950.00	1032.47	1241.31	1047.19
$MS_{BRY}=$	1271.20	1046.40	1288.14	1399.49	1100.00	1181.17	1420.06	1198.01

Table 5.2: Safety margins results of fitting 1.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}=$	3E+12	2E+12	9E+12	2E+12	4E+12	2E+12	3E+12	1E+13
$MS_{LUG,TU}$ =	4E+12	3E+12	1E+13	4E+12	6E+12	4E+12	5E+12	2E+13
$MS_{LUG,Y}=$	3E+12	2E+12	9E+12	2E+12	4E+12	2E+12	3E+12	1E+13
Transversal load:								
$MS_{LUG,TRU}=$	4.70	4.70	4.70	4.79	4.73	4.82	4.79	4.81
$MS_{LUG,TY}=$	8.31	8.31	8.31	8.46	8.35	8.50	8.45	8.49
Fitting Strength								
$MS_{FLG-BEND}$ =	6.77	4.12	6.76	6.89	4.14	4.23	6.88	4.22
$MS_{FLG-SHR}$ =	10E+12	6E+12	3E+13	9E+12	2E+13	9E+12	1E+13	4E+13
$MS_{FLG-VM}=$	6.77	4.12	6.76	6.89	4.14	4.23	6.88	4.22
Fitting Base								
Bearing								
MS_{BRU} =	1E+13	5E+12	4E+13	9E+12	1E+13	8E+12	1E+13	4E+13
MS_{BRY} =	1E+13	6E+12	4E+13	1E+13	2E+13	9E+12	1E+13	4E+13

Table 5.3: Safety margins results of fitting 2.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}$ =	262.27	266.97	266.97	298.87	281.16	315.20	304.97	321.54
$MS_{LUG,TU}$ =	260.58	265.25	265.25	296.95	279.35	313.17	303.01	319.48
$MS_{LUG,Y}=$	260.58	265.25	265.25	296.95	279.35	313.17	303.01	319.48
Transversal load:								
$MS_{LUG,TRU}=$	1.08	1.08	1.08	1.07	1.08	1.08	1.07	1.08
$MS_{LUG,TY}=$	2.22	2.22	2.22	2.21	2.23	2.21	2.21	2.21
Fitting Strength								
$MS_{FLG-BEND}$ =	2.56	1.52	2.57	2.55	1.52	1.51	2.56	1.51
$MS_{FLG-SHR}$ =	52.44	52.50	52.50	52.29	52.62	52.41	52.35	52.46
MS_{FLG-VM} =	2.55	1.51	2.56	2.54	1.52	1.51	2.55	1.51
Fitting Base								
Bearing								
MS_{BRU} =	43.29	36.24	43.33	43.17	36.00	36.19	43.21	36.22
$MS_{BRY}=$	49.66	41.60	49.71	49.52	42.00	41.54	49.57	41.58

Table 5.4: Safety margins results of fitting 3.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}$ =	160.67	162.43	162.43	173.76	167.60	179.19	175.82	181.23
$MS_{LUG,TU}$ =	159.63	161.38	161.38	172.64	166.52	178.03	174.69	180.06
$MS_{LUG,Y}=$	159.63	161.38	161.38	172.64	166.52	178.03	174.69	180.06
Transversal load:								
$MS_{LUG,TRU}$ =	1.21	1.22	1.22	1.20	1.22	1.20	1.20	1.20
$MS_{LUG,TY}=$	2.43	2.43	2.43	2.41	2.43	2.41	2.41	2.41
Fitting Strength								
$MS_{FLG-BEND}$ =	2.79	1.68	2.80	2.77	1.68	1.66	2.78	1.66
$MS_{FLG-SHR}$ =	55.75	55.81	55.81	55.49	55.79	55.47	55.54	55.52
MS_{FLG-VM} =	2.78	1.67	2.78	2.76	1.67	1.66	2.76	1.66
Fitting Base								
Bearing								
MS_{BRU} =	46.03	38.55	46.08	45.82	39.00	38.32	45.86	38.35
MS_{BRY} =	52.80	44.24	52.85	52.55	44.00	43.97	52.60	44.01

Table 5.5: Safety margins results of fitting 4.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}$ =	120.26	120.96	120.96	125.36	123.01	127.37	126.12	128.11
$MS_{LUG,TU}=$	178.26	187.57	179.29	185.79	190.73	197.47	186.93	198.62
$MS_{LUG,Y}=$	120.26	120.96	120.96	125.36	123.01	127.37	126.12	128.11
Transversal load:								
$MS_{LUG,TRU}=$	60.08	59.19	59.19	55.50	56.29	52.97	54.72	52.27
$MS_{LUG,TY}=$	98.71	97.26	97.26	91.24	92.53	87.10	89.97	85.96
Fitting Strength								
$MS_{FLG-BEND}$ =	74.46	48.21	73.54	69.76	46.19	43.90	68.93	43.41
$MS_{FLG-SHR}$ =	395.13	397.41	397.41	411.77	404.09	418.34	414.28	420.75
MS_{FLG-VM} =	72.82	47.75	71.98	68.51	45.80	43.59	67.74	43.10
Fitting Base								
Bearing								
MS_{BRU} =	489.44	399.77	492.27	510.05	406.49	420.82	513.16	423.25
$MS_{BRY}=$	560.01	457.43	563.24	583.59	465.13	481.52	587.14	484.29

Table 5.6: Safety margins results of fitting 5.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}$ =	1E+13	7E+12	1E+09	1E+09	1E+13	1E+09	9E+12	1E+09
$MS_{LUG,TU}$ =	2E+13	1E+13	1E+05	1E+05	2E+13	1E+05	1E+13	1E+05
$MS_{LUG,Y}=$	1E+13	7E+12	1E+05	1E+05	1E+13	1E+05	9E+12	1E+05
Transversal load:								
$MS_{LUG,TRU}$ =	36.73	36.40	36.40	34.81	36.39	34.80	34.51	34.51
$MS_{LUG,TY}$ =	60.59	60.06	60.06	57.46	60.04	57.45	56.97	56.96
Fitting Strength								
$MS_{FLG-BEND}$ =	51.96	33.66	51.51	49.27	33.65	32.18	48.85	31.90
$MS_{FLG-SHR}$ =	4E+13	2E+13	3E+18	3E+18	3E+13	3E+18	3E+13	3E+18
MS_{FLG-VM} =	51.96	33.66	51.51	49.27	33.65	32.18	48.85	31.90
Fitting Base								
Bearing								
MS_{BRU} =	4E+13	2E+13	4E+18	4E+18	3E+13	3E+18	4E+13	3E+18
$MS_{BRY}=$	5E+13	2E+13	5E+18	4E+18	4E+13	4E+18	4E+13	3E+18

Table 5.7: Safety margins results of fitting 6.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Lug Analysis								
Axial load:								
$MS_{LUG,BRU}$ =	3E+13	1E+12	1E+09	2E+12	1E+12	3E+12	2E+12	5E+13
$MS_{LUG,TU}$ =	3E+13	1E+12	1E+05	2E+12	1E+12	2E+12	2E+12	4E+13
$MS_{LUG,Y}=$	3E+13	1E+12	1E+05	2E+12	1E+12	2E+12	2E+12	4E+13
Transversal load:								
$MS_{LUG,TRU}$ =	1.24	1.24	1.24	1.25	1.24	1.26	1.26	1.26
$MS_{LUG,TY}$ =	2.46	2.46	2.46	2.49	2.47	2.49	2.49	2.49
Fitting Strength								
$MS_{FLG-BEND}$ =	6.58	3.63	6.58	6.64	3.63	3.66	6.64	3.66
$MS_{FLG-SHR}$ =	1E+14	6E+12	3E+17	8E+12	5E+12	1E+13	8E+12	2E+14
MS_{FLG-VM} =	6.58	3.63	6.58	6.64	3.63	3.66	6.64	3.66
Fitting Base								
Bearing								
MS_{BRU} =	6E+04	5E+04	6E+04	6E+04	5E+04	5E+04	6E+04	5E+04
MS_{BRY} =	7E+04	6E+04	7E+04	7E+04	6E+04	6E+04	7E+04	6E+04

Table 5.8: Safety margins results of fitting 7.

From observing the results in the tables above, firstly, it is noticeable that all the fittings are able to withstand the applied loads for all the hypotheses. Secondly, it is possible to confirm the safety margin reduction in some of the failures modes. One example is the fitting strength due to the bending, which the safety margin goes from 2.56 in the initial design to 1.51 in the last hypothesis on fitting three, thus this is the critical value obtained and the fitting three is the critical fitting, however, it is still in a safe zone.

The critical values for all the fittings are highlighted in blue and bold. Lastly, looking at all the values of the seven hypotheses, the accentuated safety margin reduction always occur for the hypotheses where the fittings are modified.

Regarding the von mises stress in all the fittings, from *FEMAP* it was possible to find out the most stress fitting - fitting 3. Figure 5.3 presents the outputs for the initial design and hypothesis seven , from which were extracted the maximum values of von mises stress to calculate the safety margins, where the maximum values are in red. Table 5.9 presents the final results of the safety margins.



(a) Initial design

(b) Hypothesis 7

Figure 5.3: Von Mises stress output for fitting 3 in the initial design and last hypothesis in FEMAP.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Von Mises Stress								
$MS_{Fitting3}$ =	0.97	0.11	0.97	0.99	0.12	0.11	0.99	0.12
$MS_{Fitting7}$ =	0.60	0.27	0.60	0.62	0.28	0.27	0.62	0.27

Table 5.9: Safety margins results of critical fittings for the von mises stress extracted from the FEM model.

Analysing the results, it confirms what was stated before, the fitting 3 is the most critical one inside of the safe zone. In addiction, it is confirmed that the pockets in the web of the fittings does not create critical peak of stress in the steps areas. This peak is still on the bending radius area, which does happens in the initial fitting for the initial design.

Regarding the doublers, the analysis performed showed that the doubler three is the most critical. Table 5.10 presents the safety margins results for that doubler.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
MS_{BRU} =	2.69	2.68	2.42	2.67	2.42	2.67	2.42	2.42
Von Mises Stress								
MS=	0.04	0.05	0.04	0.04	0.02	0.05	0.01	0.02

Table 5.10: Safety margins results of critical doubler - Doubler 3.

Observing the results of table 5.10, the doubler three is the component with the lowest safety margin, with a value of 0.02 for the hypothesis seven. In spite of, being very close to the ultimate allowable load, it stills be under it, so it remains in the safe zone. Furthermore, it is known that the load case applied is conservative, so it is concluded that the doubler has sufficient strength.

Lastly, it is presented the intercostals results, from intercostals on fittings one to seven, in tables 5.11 to 5.17.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
$MS_{BRG,U}=$	12.54	12.51	12.51	9.88	12.41	9.81	9.86	9.79
$MS_{BRG,Y}=$	13.29	13.26	13.26	10.48	13.15	10.40	10.46	10.38
Tensile and Compressive								
Stress in Flanges								
$MS_T =$	14.21	14.18	14.18	11.01	14.07	10.92	10.98	10.90
$MS_C =$	18.60	18.56	18.56	14.60	18.42	14.49	14.57	14.46
Maximum Shear Web								
$MS_{SHR,WEB}$ =	13.85	13.81	13.81	10.93	13.71	10.85	10.91	10.83

Table 5.11: Safety margins results of intercostals in fitting 1.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
$MS_{BRG,U}=$	9.43	9.42	9.42	7.46	9.47	7.50	7.46	7.49
$MS_{BRG,Y}=$	10.00	9.99	9.99	7.93	10.04	7.97	7.92	7.96
Tensile and Compressive								
Stress in Flanges								
$MS_T =$	10.71	10.70	10.70	8.33	10.76	8.38	8.33	8.37
MS_C =	14.10	14.08	14.08	11.13	14.15	11.18	11.12	11.17
Maximum Shear Web								
$MS_{SHR,WEB}$ =	10.43	10.42	10.42	8.28	10.48	8.32	8.27	8.31

Table 5.12: Safety margins results of intercostals in fitting 2.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
$MS_{BRG,U}=$	3.83	3.83	3.83	3.81	3.84	3.82	3.82	3.83
$MS_{BRG,Y} =$	4.09	4.10	4.10	4.08	4.11	4.09	4.08	4.10
Tensile and Compressive								
Stress in Flanges								
MS_T =	4.30	4.30	4.30	4.28	4.31	4.29	4.29	4.30
MS_C =	5.83	5.83	5.83	5.81	5.85	5.82	5.82	5.83
Maximum Shear Web								
$MS_{SHR,WEB}=$	4.29	4.30	4.30	4.28	4.31	4.29	4.28	4.30

Table 5.13: Safety margins results of intercostals in fitting 3.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
$MS_{BRG,U}=$	4.18	4.19	4.19	4.15	4.18	4.15	4.16	4.15
$MS_{BRG,Y}=$	4.47	4.47	4.47	4.44	4.47	4.43	4.44	4.44
Tensile and Compressive								
Stress in Flanges								
$MS_T =$	4.69	4.69	4.69	4.65	4.69	4.65	4.66	4.65
$MS_C =$	6.33	6.34	6.34	6.29	6.33	6.28	6.29	6.29
Maximum Shear Web								
$MS_{SHR,WEB}$ =	4.68	4.69	4.69	4.65	4.68	4.65	4.66	4.65

Table 5.14: Safety margins results of intercostals in fitting 4.

Hypotheis ID	Initial	1	2	3	4	5	6	7
Bearing	Design							
Dearing		440 74		~~~~	100.01	70.00	00 0 7	
$MS_{BRG,U}=$	114.54	112.74	112.74	83.92	106.91	79.88	82.67	/8.//
$MS_{BRG,Y}=$	120.90	119.01	119.01	88.59	112.85	84.33	87.28	83.17
Tensile and Compressive								
Stress in Flanges								
$MS_T =$	128.09	126.08	126.08	92.16	119.56	87.73	90.79	86.52
MS_C =	165.34	162.76	162.76	120.02	154.36	114.26	118.24	112.69
Maximum Shear Web								
$MS_{SHR,WEB}$ =	125.68	123.71	123.71	92.11	117.32	87.68	90.74	86.47

Table 5.15: Safety margins results of intercostals in fitting 5.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
$MS_{BRG,U}=$	66.78	66.20	66.20	50.42	66.18	50.41	49.99	49.98
$MS_{BRG,Y}=$	70.51	69.90	69.90	53.25	69.88	53.24	52.80	52.79
Tensile and Compressive								
Stress in Flanges								
$MS_T =$	74.73	74.08	74.08	55.41	74.06	55.40	54.94	54.93
$MS_C =$	96.59	95.75	95.75	72.28	95.73	72.27	71.67	71.66
Maximum Shear Web								
$MS_{SHR,WEB}$ =	73.32	72.68	72.68	55.38	72.66	55.37	54.91	54.90

Table 5.16: Safety margins results of intercostals in fitting 6.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Bearing								
$MS_{BRG,U}$ =	3.45	3.45	3.45	2.58	3.46	2.59	2.58	2.59
$MS_{BRG,Y}=$	3.70	3.70	3.70	2.78	3.70	2.78	2.78	2.79
Tensile and Compressive								
Stress in Flanges								
$MS_T =$	4.20	4.20	4.20	3.11	4.20	3.11	3.11	3.11
MS_C =	5.70	5.70	5.70	4.34	5.70	4.34	4.34	4.34
Maximum Shear Web								
$MS_{SHR,WEB}$ =	3.88	3.88	3.88	2.93	3.89	2.93	2.93	2.93

Table 5.17: Safety margins results of intercostals in fitting 7.

Observing the results in the tables above, firstly, it shows that all the intercostals are able to withstand the applied loads for all the hypothesis. Secondly, it is possible to confirm the safety margin reduction in some of the failures modes in the successive hypotheses. The intercostals in fitting seven presented the lowest safety margins, however the analytical method used does not account for the cut-out in intercostals in fitting three and four. So, to verify which are the critical intercostals it is necessary to verify in the FEM results with the von mises stress for instance. It can be expected that due to the cut-out on intercostals of fitting three and four, there will be a peak of stress on the fillets of the cut-out of these intercostals, so these probably will have the lowest safety margin. This will be verified in the next paragraphs.

Similarly to the fittings, the von mises stress in all the intercostals were extracted from *FEMAP* and it was possible to find out the most stress intercostal - the cut-outed intercostal in fitting 3. Figure 5.4 presents the outputs for the initial design and hypothesis seven, from which were extracted the maximum values of von mises stresses to calculate the safety margins, where the maximum values are in red. Table 5.18 presents the final results of the safety margins.



(a) Initial design

(b) Hypothesis 7

Figure 5.4: Von Mises stress output for the critical intercostal in the initial design and last hypothesis in *FEMAP*.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Von Mises Stress								
MS=	0,15	0,15	0,14	0,15	0,14	0,15	0,14	0,14

Table 5.18: Safety margins results of critical intercostal for the von mises stress extracted from the FEM model.

Analysing the results, it confirms what was stated before, the intercostal in fitting 3 is the most critical one. However, the safety margin is still higher than zero, this means that the intercostal is still able to withstand the load.

In terms of all the other structural components, such as, mounting gussets, frames and fasteners, it was verified that the safety margins are positive. The results for the critical components can be found in annex A. So, anything of these components is turning the seven hypotheses designs unfeasible. Therefore, for the static point of view, all the setted hypotheses are able to withstand the applied loads, therefore are structurally feasible.

5.3 Fatigue

The goal of the fatigue analysis performed is to determine the number of cycles of fatigue life of the fittings and doublers of the seven hypotheses under the fatigue load case, in order to verify if this number is larger than the OEM imposed threshold number of cycles. To achieve this, firstly, the value of the maximum principal stress in the fittings and the respective nominal stress in the web fitting were extracted to estimate the fittings' fatigue life. Figure 5.5 presents the maximum principal stress output from *FEMAP* for the most critical fitting. It was found out that fitting three is under the most critical stress condition. Figure 5.6 presents a graphic with the fitting three fatigue life for the seven hypothesis. In addition, table 5.19 details the values obtained.



(a) Initial design

(b) Hypothesis 7

Figure 5.5: Maximum principal stress output for the critical fitting in the initial design and last hypothesis in *FEMAP*.



Figure 5.6: Fatigue life's number of cycles of fitting 3 for the initial design and the seven hypotheses.

Hyphothesis ID	0	1	2	3	4	5	6	7
Number of cycles	1070961	71398	680111	676539	71782	71547	680111	71911

Table 5.19:	Number	of	cycles	of	fatigue	life.

Observing the results, firstly, it shows that the fitting modification decreases the number of cycles in 93% due to the increase of the maximum principal stress in the base of the fitting. On the other hand, the number of cycles for the modified fitting still acceptable, because is above the limit of 24000 flight cycles imposed as threshold by Airbus for the aircraft models A319 and A320. This value is obtained by equation $N_{th} = 0.5 \times DSG$ provided in the Airbus structure training manual, where DSG is the Design Service Goal and is equal to 48000 flight cycles for the mentioned aircraft. These information is given in the Airbus fatigue stress manual [26].

Regarding the doubler, firstly, it was extracted the loads in the skin from the complete FEM model, to build the small model with the doubler two for the fatigue analysis. The conclusion of this extraction was the same for the static analysis, the loads for the seven hypothesis remains the same due to the low

change in the inertia of the installation. Thus, it was used the initial design loads in the model for all the hypotheses. The results obtained are presented in figure 5.7 and table 5.20.



Figure 5.7: Number of cycles of fatigue life for Doubler 3 for the seven hypotheses.

Hyphothesis ID	0	1	2	3	4	5	6	7
Number of cycles	178740	167345	150107	160490	150597	161091	145079	145563

Table 5.20: Number of cycles of fatigue life for doubler 2 for the initial design and seven hypothesis.

The results shows a reduction in the number of cycles for all the hypothesis, having the maximum reduction in the hypothesis where the doubler with a reduced thickness is employed. In addition, it also shows the impact of changing the intercostals and the fittings in terms of doubler's fatigue life, with a reduction of 10% and 6% of number of cycles, respectively. In spite of that reduction, all the hypotheses have the number of cycles above the threshold imposed again by Airbus of 24000 flight cycles.

Cross checking the obtained results for the fittings and doublers, it shows that with the fitting modification, this component became the critical one in terms of fatigue life, due to the huge reduction of the number of cycles. Therefore, the fatigue life of hypothesis 1, 4, 5 and 7 is driven by the fittings and not the doublers as in the initial design. The other hypotheses continue to be driven by the doubler and does not introduce a huge reduction in the number of cycles. Table 5.21 summarize the critical values of the number of cycles for all hypotheses.

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Number of cycles	178740	71398	150107	160490	71782	71547	145079	71911
Critical Component	Doubler	Fitting	Doubler	Doubler	Fitting	Fitting	Doubler	Fitting

Table 5.21: Critical number of cycles of fatigue life which drives each hypothesis.

5.4 Optimal hypothesis

Once all the results are presented, it is time to decide which is the optimum hypothesis to go for. This decision is a compromise between several requirements, such as, the certification, the business and the company internal requirements. The business ones are traduced by the customer requirements, where there will be two possible scenarios. Or the customer is an airliner or a private one. In case of an airliner as a customer, it is known that the goal of an airline is to make profits in their flights, so less weight introduced in the aircraft means less fuel consumption, which reflects in less operational cost, so for an airliner the main requirement is the weight reduction. On the other hand, for a private customer which is not worried about weight but is concerned about extra costs, the inspections interval are the main requirement, the design provided must guarantee that the customer will not have extra costs in terms of maintenance due to shorts intervals of inspection and the aircraft must be on ground only because of the antenna. Regarding the internal requirements, these will influence the developed design. Examples of these requirements are the capacity of the company to produce a certain design and also if the company has the knowledge required for the development of that.

To support in the decision normally a graphic named pareto front is produced, where from two variables are plot the several hypothesis to be easy to cross check the results and confirm what is optimum decision according to the weight given for each variable. Figure 5.8 presents the graphic with the critical fatigue life number of cycles which drive each hypothesis versus the weight reduction.



Figure 5.8: Pseudo Pareto Front - Critical fatigue life's number of cycles VS Weight reduction.

Observing the graphic above, it is possible to see that there are two groups of sets of hypotheses, one close to the 1% weight reduction and another close to the 9%. The first group is composed by hypothesis 1 (F), 2 (D) and 4 (F+D). Furthermore, hypotheses 1 and 4 in this group has a reduction in the fatigue life comparable to other hypothesis with higher weight reduction percentage. Thus, these hypothesis are far to be the preferable ones. The second group is composed by hypothesis 3 (I), 5 (F+I), 6 (D+I) and 7 (F+D+I). From these hypothesis, the number seven is the one which improve more in terms weight reduction, however has a reduction impact of 59.8% in the number of cycles. The optimum option

can be hypothesis 6 which has 9.2% of weight reduction and the impact in the reduction of number of cycles is lower compared with the hypothesis seven, 18.8% for this hypothesis .

Regarding the last requirement, the certification, all these design hypotheses are not certifiable yet because it is necessary to prove that the hypotheses can withstand all the other mentioned load cases in section 4.2 and for this study it was only considered the load case one which is good representation of the critical load cases but is not enough. In addiction, a damage tolerance analysis must be performed in order to find the inspection intervals, performing only a fatigue analysis is not enough again for certification. In spite of that, this initial study gives good indications which improvements can be done in the initial design in order to achieve higher quality values.

Chapter 6

Design Initial Release

Reaching to the final stage, once the structural analyses are completed, the solution design is converted in 2D drawings. These are composed by the installation drawing and the drawings of each part which compose the structural installation solution. When all the drawings are completed and released by the engineering, this moment is known as the Initial Release. This means that the installation's technicians and production department can start their functions. However, before the technicians can start the installation, the part's drawings go for the production department to manufacture the parts. Once all parts are produced, the installation can start and the engineering work in field as well, by giving support to the technicians to solve some unexpected deviations which were not accounted for in the design because of the differences between a green and real aircraft, in order to not to stop the installation. In the meanwhile, the engineering work also continues in the office by producing and finalizing the certification documents which prove that all the requirements are complied and also will allow the aircraft to perform a flight test to conduct some experimental tests. These three topics, installation's deviations, experimental tests and certification documents are developed in section 6.1, 6.2 and 6.3, respectively.

6.1 Installation's Deviations

In any kind of project where is necessary to install a new feature in the existing environment, it is normal that unexpected deviations will occur, because of the complexity of the environment is hard and costly to have a complete and detailed 3D model of it. Additionally, the information about the environment sometimes is not available which makes the process even more complex.

In order to solve the deviations, there are three actions that can be performed. The first is proceed with revision of the drawing and update the drawing with the deviations. The second is to create a deviation sheet. And the last is to perform a concession. These three options will be explored in the following paragraphs.

Drawing Revision

Every time a drawing is produced this starts in revision A. In a scenario where there is a deviation and this drawing is impacted, one of the solution is to revise the drawing, going to the revision B. To perform this, the engineer works closely with the technicians and there is a process of reverse engineering, where from the installation are taken the new impacted data and the drawing is updated with the new information, so there is a reversal of the usual process. Furthermore, this method is used when the drawings will be reused more times, so in order not to prepare a deviation sheet every time that an aircraft is being modified with those drawings. In terms of time, this type of solution can take a considerable time to perform.

Deviation Sheet

Every project has its own deadlines and the time is money for the company. So can happen in the middle of the rush, to accomplish the deadline, appears an deviation, and it is necessary to quickly act in order to do not stop the work flow. The solution used in this kind of situations, and the most commonly used is to create a deviation sheet which can be performed faster than revise the drawing. A deviation sheet is composed in three sections. In the first is presented the issue and the solution to solve it, in the second is illustrated which part of the drawing is modified, by showing how was and how is now the drawing. In the last section is presented the modifications in the drawing's Bill Of Materials (BOM). The BOM is a product structure, where all the parts and assemblies are described, along with their properties (e.g.: quantities, material, dimensions), needed to manufacture the final product.

Concession

The last type solution happens when there is a deviation but this is not reported to engineering during the installation process, this is actually included in a document prepared by the technicians department to be approved after by the engineering before the aircraft leaves the company. Only small deviations where engineering does not need to be called can be solved by a concession.

The number of deviations can give a measure on how the design can be flexible within the limits in order to absorb the deviations. A lot of strategies can be used in order to give more flexibility to the design. One for example, when there are fasteners placed in a part, these parts can be designed a few larger in order to give more freedom to the technician place it respecting the design rules. With this, there are more possibilities to install the fasteners, so there is less probability to the installation get stack because of the impossibility of installing the fasteners. The general good practise to reduce the number of deviations, starts by identifying which parts can be more susceptible to suffer a deviation and anticipate it by changing these parts to new ones which are more robust.

Having a flexible design, the probability of the installation get stuck and requirement of the engineering action is lower, this means that the installation process goes faster and without problems. In terms of the company point of view, it decreases the required engineering time, which means a reduction of the costs and so that an increase of the profits.

6.2 Experimental Tests

Regarding the certification, there are two forms of showing compliance to the requirements. One is by the use of FEM models and approved literature, case of the strength analysis, methodology used in this work, and other is by the use of experimental tests, for instance a flight test, case of the test for vibrations and buffeting performed after the antenna installation is completed.

This test was conducted in the Jet Aviation initial design installed in the aircraft described in section 1.6 by installing sensors, to measure the acceleration in the frames where the provisions are installed. This test aims to prove that for a certain range of frequencies (0-100Hz) in specific flight conditions, there will not occur any dynamic phenomena as resonance in aircraft airframe due to the installation of the new system. Figure 6.1 presents one of the results for steady flight at 39000 feet.



Figure 6.1: Vibration Results from the flight test for a specifique frame with the acceleration in Y direction [15].

Figure 6.1 plus the rest of the results which are not presented here show that no particular frequency is subject to pikes of vibration energy indicating resonance or flutter for the range of frequencies of interest, below the 100Hz. Thus, the installation complies with the vibration and buffeting requirements for certification.

6.3 Certification Documents

The last stage, before apply for the STC is to prepare and conclude all the required documents which will prove that all the certification requirements are being full-filled. Some of these documents were already briefly introduced in section 1.2, however they will be evoked here again in order to the full spectrum of the required documents which compose the STC is presented together.

Therefore, the required documents are presented in the following list.

- CAF Classification Assessment & Application Form
- MDL Master Data List

- CCS Certification Compliance Sheet
- DLM Drawing List Mechanical
- DLE Drawing List Electrical
- EIL Electrical Item List
- ENO Engineering Order
- WBS Weight and Balance Statement
- SSR Structural Substantiation Report
- DTA Damage Tolerance Analysis
- ANA Analysis Report
- DPS subcontractor Document Process Slip
- FTP/R Flight Test Plan / Report
- ICA Instructions for Continued Airworthiness

These documents cover several areas, then as a result, each specific department is responsible for certain documents. For example, the DLMs and WBSs are only responsibility of mechanical department. The DLEs and EILs are prepared by the electrical department and the SSRs and DTAs are prepared by the stress department. Some documents have the contribution of two different departments, which are the case of ENO, ANA, CCS and ICA. All these documents will be presented and described in more detailed in the next paragraphs, with the exception of the CAF which was already completely presented in section 1.6.

6.3.1 Master Data List - MDL

The MDL is the master document where is presented all the documentation produced for the STC. Basically, it shows the tree's structure of the documentation and its organization in order to give a clear view of all required files and help to ensure that no documents are forgotten.

6.3.2 Certification Compliance Sheet - CCS

The CCS is the document which summarize all information related to certification concerning a specific aircraft's modification. Therefore, it presents the applicable certification paragraphs which must been shown compliance and the respective documents which prove that certification requirements are been full-filled.

6.3.3 Drawing List Mechanical - DLM

The DLM is the document where all the mechanical drawings required for the modification must appear. Essentially, it is a sub master document which groups all the produced drawings in order to be called by other documents and justify certain certification requirements. There are the situations when the drawing does not include the bill of materials inside, this needs to be added as a second document. Therefore, in these situations, two documents must be added to the DLM, the drawing and respective BOM. Additionally, in the DLM, revision and release date of the drawings and BOMs must also appear, otherwise, these will not be validated.

6.3.4 Drawing List Electrical and Electrical Item List - DLE and EIL

Similar to the mechanical side, electrical has to prepare a document where all the electrical drawings produced are integrated. The content of these drawings is the definition of the connections between the different components and the respective wire types and routings. This document is denominated as Drawing List Electrical. On top of that, an Electrical Item List also must be prepared. The EIL includes all the electrical equipment which will be installed in the modification, for instance, the ka-band systems, kandu, krfu and others, all of them are mentioned in this document.

6.3.5 Engineering Order - ENO

The ENO is the document which states the actions that must be performed in order to the modification be completed. As it was referred before, this document is prepared by two different departments, mechanical and electrical. As a result, the document is divided in several parts, some from the mechanical side's responsibility, for instance, the section of new parts to manufacture, removals and re-works. On the other hand, the sections from electrical side's responsibility, as example, the indication of the tests that must be performed, in order to see if the installed electrical equipment is functional. To sum up, this document is a work order which describes all the steps to complete the modification and in the end must be signed by the in-charged person on the technical side and be returned to the engineering.

6.3.6 Weight and Balance Statement - WBS

When there is a modification in an aircraft, its weight can suffer alteration, the weight can increase or decrease. In these two possible situations, a document denominated as weight and balance statement must be prepared in order to present all the added or removed weights, the respective balance arms and produced moments. The WBS is an extremely important document for two reasons. Firstly, it presents the new state of the aircraft in terms of weights which will impact the centre of gravity of the aircraft and therefore, the pilots before departure need to take into account this new state of the aircraft in order to know where is the CG and have that in mind for the aircraft's stability and fuel consumption optimization. Secondly, is related to the additional produced bending moments, which need to be added to the aircraft's original bending moment, in order to be possible to perform reliable analyses with the

accurate loads. Nonetheless, for minor modifications the increase of weight can be so small, that it will not have an impact on the CG location or the bending moment.

6.3.7 Structural Substantiation Report and Damage Tolerance Analysis - SSR and DTA

The SSR is the document where all the structural analyses performed are presented. These mainly include the strength analysis of the external components (radome, adapter plate and female fittings) and internal structural components (male fittings, doublers, mounting gussets and intercostals) and also, vibration analysis to confirm the structure's structural integrity in case of phenomena like windmilling. In addiction, there is also the DTA document where is reported the fatigue study of the most suitable components for crack propagation. With the result to present the new intervals of inspection for the modification. The final result of the work developed in this thesis could be used as a content of these two documents.

6.3.8 Analysis Report - ANA

Several other analyses must be performed in order to prove that certain certification paragraphs are being complied. These analyses are presented in the documents' type of Analysis report. From the different analysis that can be performed, there are, for instance, the bird strike and de-icing analysis. Additionally, there is another type of analysis that was already mentioned in the paragraph "obstruction light" in section 3.2, the beacon anti-collision light analysis. In this analysis, must be shown that the addition of the antenna system will not obstruct the light from the beacon more than a solid angle of 0.03 steradian. This condition is setted by the certification specification CS 25.1401. Figure 6.2 illustrates the steradian concept.



Figure 6.2: Concept of a steradian [29].

To perform this analysis, it was used the software $CATIA^{TM}$ to model the beacon position in relation to the antenna and tail and after the shape of the last two, which are the two components that creates obstruction to the light. Having the model completed it was possible to project radially the obstruction areas of the two components in a sphere with 25 meters of radius, therefore, calculate the obstruction solid angle and show that is lower to the imposed limit by certification.

6.3.9 Subcontractor Document Process Slip - DPS

Since there are structural components for the installation which come from an external supplier, all the drawings concerning this components are also provided by the supplier. Thus, these drawings have to be included in the documentation for the STC. To accomplish that, there are the DPS which are a document where all the provided drawings are listed.

6.3.10 Flight Test Plan / Report - FTP/R

After each system installation, the aircraft must do a flight test in order to collect some flight data concerning stress subjects. With the final goal to validate the theoretical results with experimental ones from the flight. Consequently, it must be prepared a FTP document stating all the conditions for the flight test and procedures. Finally, a FTR is prepared with all the post processing data from the flight and furthermore, it is presented the conclusion of the comparison between theoretical and experimental results.

6.3.11 Instructions for Continued Airworthiness - ICA

As it was already introduced in section 1.2, the ICA is the document which presents all the applicable changes in terms of maintenance instructions with the installation of the new system, as well as, the new intervals of inspection for each new part and existing touched environment. In addition, it also presents the new airworthiness limitations for all the new structural provisions along with the specific inspection method. Finally, in the ICA are also identified the new fatigue critical structures.

Once all the documents are prepared and released, the modification can be closed and the process for the STC application can go forward to the competent regulatory body to approve the modification applicable for elected aircraft types. To sum up, in one shot, it was developed four different installations to sell in the future for customers with A319 or A320 series aircraft.

Now, it is possible to proceed with the final chapter, to establish the conclusions of the developed work.

Chapter 7

Conclusions

7.1 Achievements

Several achievements have been fulfilled in this work, starting with the demonstration of the benefits for the industry by using a standard as the ARINC 791 for the ka-band antenna, which is the base of the design developed by Jet Aviation.

Secondly, the illustration of all the steps to certify a major modification as the installation of the kaband system was accomplished, by going through the selection of the antenna location, the certification requirements, the mechanical design development, the installation and respective deviations, the flight test and the documentation required for the Supplemental Type Certificate (STC) application.

Thirdly, the major achievement in this work was the results obtained from the static and fatigue analysis for the seven set hypotheses in the parametric optimization. The results proved that all designs are strong enough to withstand the selected critical load case, rapid decompression of the radome. All the structural components presented a safety margin higher than zero. In terms of fatigue, the alterations introduced in the fittings, doubler and intercostals led to a reduction of the fatigue life for all the hypotheses, although without any negative impact on the Airbus threshold. As final result, hypotheses number six - design with modified doublers and intercostals - was considered the optimal due to the high percentage of weight reduction and low reduction of the fatigue life number of cycles. To sum up, this initial parametric optimization was useful to find an optimal design which can be an option in the future. However, further analyses must be conducted to verify the structural integrity for other load cases and to determine the threshold and intervals of inspection in order to be a certified design.

Lastly, the important role played by the experimental flight test in the certification of the initial design of Jet Aviation was shown. The obtained results during the flight test covering the vibration and buffeting requirement proved that any peaks of vibration energy indicating resonance or flutter occurs within the required range of frequencies. With these results plus the numerical ones was achieved a certified solution, where an EASA Supplemental Type Certificate was issued with the number 10071445, named as "KA Band Satcom System" applicable for the Airbus A319 and A320 series aircraft on the rear fuselage.

7.2 Future Work

As a future work, there are two identified opportunities.

The first one is to continue the scope of the present work, where the static analysis for the remaining loads cases could be performed in order to prove that all the seven hypotheses are strong enough under all the load cases. In addiction, the damage tolerance analysis could also be conducted in order to find the intervals of inspections required for certification. With these two topics covered, the results could show if all the hypotheses are certifiable designs or not.

The second option is to take the initial design developed at Jet Aviation and update it for the new standard ARINC 792, where there were 7 fittings interfacing the antenna and the aircraft airframe, there would be only six fittings, the most backward, the number seven having been removed. An initial study could be performed to verify if the updated design is still feasible in terms of stress and certificability. In case of a negative result, what changes could be performed in the design in order to make it feasible.

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Appendix A

Additional data

In the next sections are presented graphics and figures with data used in the developed study.

A.1 Geometrical dimensions of the modified fittings

Lug Typ	e	Male						
Lug Diameter	D [mm]	20,600	20,600	20,600	20,600	20,600	20,600	20,600
Lug Thickness	t _{F-GROSS} [mm]	8,800	8,800	8,800	8,800	8,800	8,800	8,800
Lug Effective Thickness	t [mm]	7,920	7,920	7,920	7,920	7,920	7,920	7,920
Lug Ext Rad	a [mm]	20,1	20,1	20,1	20,1	20,1	20,1	20,1
Lug Width	W [mm]	52,4	53,1	41,1	41,1	52,5	52,5	40
Gap ; slipering rage	g [mm]	4,572	7,544	4,572	4,572	4,572	7,544	6,426
Base Thickness	t _B [mm]	5,000	5,000	5,191	5,191	5,000	5,000	5,000
Base Length	L _B [mm]	80,000	90,512	80,000	80,000	80,000	80,000	110,500
Distance Brg Length	L _{B-B} [mm]	70,412	70,412	40,000	40,000	53,872	53,872	55,250
Base Width	b _B [mm]	66,386	66,386	73,232	73,232	66,800	66,800	62,800
Bearing to Base distance	h _B [mm]	30,856	30,856	43,942	43,942	30,975	30,975	18,516
Fitting angle	θ [°]	90,000	90,000	78,273	78,273	90,000	90,000	90,000
Distance center- edge	d _B [mm]	33,193	33,193	31,935	31,935	33,400	33,400	31,400

Figure A.1: Modified fittings geometrical dimensions.

Thickess	t _{INT} [mm]	2,0	2,0	2,0	2,0	2,0	2,0	2,0
Height	H _{INT} [mm]	95,3	95,3	95,3	95,3	95,3	95,3	95,3
Outer Flange	L _{OUT-FLG}	15,2	15,2	15,2	15,2	15,2	15,2	15,2
Outer Flg Lip	L _{OUT-FLG-}	0,0	0,0	0,0	0,0	0,0	0,0	0,0
Inner Flange	L _{IN-FLG} [mm]	27,9	27,9	27,9	27,9	27,9	27,9	27,9
Inner Flg Lip	L _{IN-FLG-LIP}	13,0	13,0	13,0	13,0	13,0	13,0	13,0
Bending Radius	R [mm]	7,0	7,0	7,0	7,0	7,0	7,0	7,0
Intercostal Length	L [mm]	489,60	489,60	489,60	489,60	489,60	489,60	489,60
Segment 1 Length	L ₁ [mm]	204,600	204,600	230,000	230,000	280,800	280,800	306,200

A.2 Geometrical dimensions of the modified intercostals

Figure A.2: Modified intercostals geometrical dimensions.

A.3 Shear-Bearing Efficiency Factor - *K*_{br}



Figure A.3: Shear-bearing efficiency factor graphic extracted from [24].

A.4 Lug Efficiency Factor for Tension - *K*_t



Figure A.4: Lug efficiency factor for tension graphic extracted from [24].

A.5 Yield Factor - C



Figure A.5: Yield factor for tension graphic extracted from [24].

A.6 Efficiency Factor for Transverse Load - k_{tru} and k_{try}



Figure A.6: Efficiency factor for transverse load graphic extracted from [24].

A.7 Bearing Stress Concentration Factor - *K*_{tb}



Figure A.7: Bearing stress concentration factor graphic extracted from [24].
A.8 Stress Concentration Factor - K_{tg}



Figure A.8: Stress concentration factor graphic extracted from [24].

A.9 Bearing Distribution Factor - θ





A.10 Stress-life (S-N) curves of aluminium 7050-T7451 plate



Figure 3.7.5.2.8(f). Best-fit S/N curves for notched, K, = 3.0, 7050-T7451 plate, longitudinal and long transverse directions, t/4 specimen location.

Correlative Information for Figure 3.7.5.2.8(f)

Product Form: Plate, 1.0 to 6.0 inches thick			es thick	Test Parameters:
				Loading - Axial
Properties:	TUS, ksi	TYS, ksi	Temp., °F	Frequency - 800 cpm and unspecified
	75-81	65-72	RT	Temperature - RT
				Environment - Air
Specimen Deta	ils: Circum	ferentially	notched,	
	K	= 3.0		No. of Heats/Lots: 11
	0.306- a	and 0.373-i	nch gross	
	di	ameter	U	Equivalent Stress Equation:
	0.253-ii	nch net diar	meter	$Log N_f = 10.0-3.96 log (S_{eq})$
	0.013-ii	nch notch-ti	ip radius, r	$S_{eq} = S_{max} (1-R)^{0.64}$
	60° flai	nk angle, ω		Std. Error of Estimate, Log (Life) = 0.248
		0		Standard Deviation, Log (Life) = 0.728
Surface Condit	ion: Not sp	pecified		$R^2 = 88\%$
References:	3.7.5.2.80	b), 3.7.5.2.8	S(c), and	Sample Size = 79
	375290	b)	())	<u> </u>
		-)		[Caution: The equivalent stress model may
				provide unrealistic life predictions for stress
				ratios beyond those represented above 1
				ratios seguna anose represented above.]

Figure A.10: Stress-life curves of aluminium 7050-T7451 plate from [25].

A.11 Safety margins results for the critical mounting gusset in fitting 7

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
End-Pad								
$MS_{Bend,U}=$	1.12	1.12	1.12	1.13	1.12	1.13	1.13	1.13
$MS_{Shear} =$	2.83	2.83	2.83	2.86	2.83	2.86	2.86	2.86
Wall								
$MS_T =$	4.51	4.51	4.51	4.55	4.51	4.55	4.55	4.55
MS_{Bend} =	0.91	0.91	0.91	0.92	0.91	0.92	0.92	0.92

Table A.1: Safety margins results of the critical mounting gusset in fitting 7.

A.12 Safety margins results for the critical frame

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Flange								
$MS_{Comp.Y} =$	0.15	0.16	0.14	0.15	0.14	0.14	0.14	0.14
Web								
$MS_{Shear,U}$ =	0.15	0.16	0.15	0.15	0.15	0.15	0.15	0.15

Table A.2: Safety margins results of the critical frame.

A.13 Safety margins results for the critical fastener - Mounting Gusset & Intercostal in fitting 7 - NAS6203

Hypotheis ID	Initial Design	1	2	3	4	5	6	7
Fastener								
MS_{Shear} =	0.15	0.16	0.14	0.15	0.14	0.14	0.14	0.14

Table A.3: Safety margins results of the critical fastener - NAS6203.